# Automation solution for simple machines
## Startup Guide

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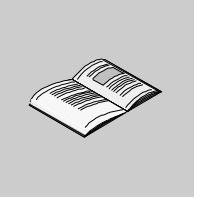


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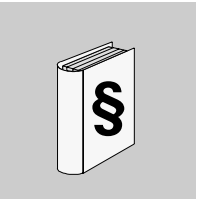
# Safety Information



## Important Information

**NOTICE**

Read these instructions carefully, and look at the equipment to become familiar with the device before trying to install, operate, or maintain it. The following special messages may appear throughout this documentation or on the equipment to warn of potential hazards or to call attention to information that clarifies or simplifies a procedure.

The addition of this symbol to a Danger or Warning safety label indicates that an electrical hazard exists, which will result in personal injury if the instructions are not followed.

This is the safety alert symbol. It is used to alert you to potential personal injury hazards. Obey all safety messages that follow this symbol to avoid possible injury or death.

**⚠ DANGER**

DANGER indicates an imminently hazardous situation, which, if not avoided, **will result** in death, serious injury, or equipment damage.

**⚠ WARNING**

WARNING indicates a potentially hazardous situation, which, if not avoided, **can result** in death, serious injury, or equipment damage.

**⚠ CAUTION**

CAUTION indicates a potentially hazardous situation, which, if not avoided, **can result** in injury or equipment damage.

**PLEASE NOTE**

Electrical equipment should be serviced only by qualified personnel. No responsibility is assumed by Schneider Electric for any consequences arising out of the use of this material. This document is not intended as an instruction manual for untrained persons.

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# Presentation of the automation solution for simple machines

# I

## At a Glance

**Overview**

This document presents installation of an automation solution for simple machines.

**What's in this Part?**

This part contains the following chapters:


| Chapter | Chapter Name | Page |
|---|---|---|
| 1 | Introduction | 11 |

# Introduction

# 1

## At a Glance

**Overview**

This chapter presents the automation system described in this document.

**What's in this Chapter?**

This chapter contains the following topics:


| Topic | Page |
|---|---|
| General | 12 |
| Technical specifications | 14 |
| Description | 17 |
| Required hardware | 18 |

## General

**Introduction**

Dedicated to simple installations and small compact machines, the programmable controller Twido, the Altivar variable speed controller, the Magelis XBTN displayer and the new Advantys OTB and FTB distributed I/O are already renowned for their ability to benefit you in terms of capacity, simplicity and competitiveness.

Today their association is a real solution, that guarantees the ease and speed of implementation as well as the prefect functioning of the whole, thanks to a package complete with cabling and well-integrated software (functional blocks integrated in TwidoSoft).

**⚠ CAUTION**

**This document does not replace in any manner the individual documentation of each product.**
It describes in simplified manner the installation, setup and implementation presented.
Descriptions and functional specifications of a specific application are not part of this document.
Nonetheless, this document presents a typical automated solution that can be used.
To facilitate system implementation, the setup files and applications necessary for the presented solution are delivered with the products.
**Failure to follow this instruction can result in injury or equipment damage.**

## Abbreviations / Terminology

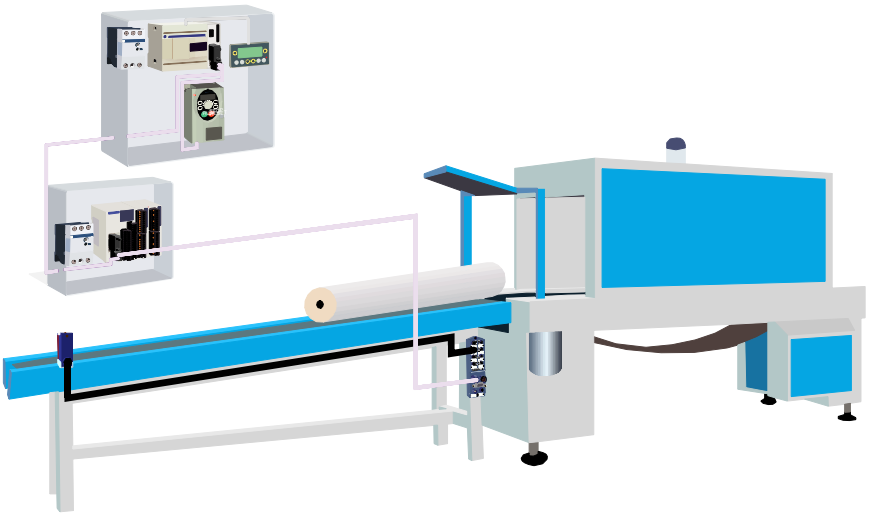
Here are the abbreviations and terms used in this document:

| Abbreviation | Description |
|---|---|
| PC | Personal |
| XBTN | Displayer with alphanumeric screen |
| ATV31 | Altivar 31 family variable speed controller |
| TAP | Derivation housing |
| OTB | Advantys OTB IP 20 I/O module |
| FTB | Advantys FTB IP67 I/O splitters |
| HMI | Human/Machine Interface |
| AC | AC power |
| DC | DC power |
| I/O | Input/Output. |
| Altivar | Name of the family that includes the Schneider variable speed controllers |
| Magelis | Name of the family that includes part of the Schneider HMI |
| Twido | Name of the family that includes part of the Schneider controllers |

## Technical specifications

### Example of an automation solution

The diagram below shows an example of an automation solution:



The procedure for automating a simple machine of this type is shown in the following table:

| For | Use |
|---|---|
| Monitor the operation, coordinate, configure and control the different sensors actuators | Twido controller |
| View and/or configure the different parameters of the application | A Magelis Human/Machine Interface |
| Operate the belt | An Altivar variable speed controller |
| Detect and control the products | of the Advantys remote inputs/outputs linked to the sensors/actuators |

To respond to these simplified technical specifications, we propose a complete solution outlined in this guide.

**Objective**

The automation solution presented in this document shows how to control one or several motors. To do this, we propose to link an ATV31 variable speed controller with a Twido controller on the CANopen bus. In fact, the Twido controller includes the Macro Drive developed for ATV31s. This Macro Drive includes micro applications that allow easy development of an application for an ATV31.

It is possible to assign a name to each of the variables used in the Twido application, called SYMBOL.

To display the parameters of the system and change the speed of a motor, a XBTN operator display is added. There is a dynamic link between the list of symbols used in the Twido application and that of the XBTN application. This dynamic link facilitates the development of the operator display application.

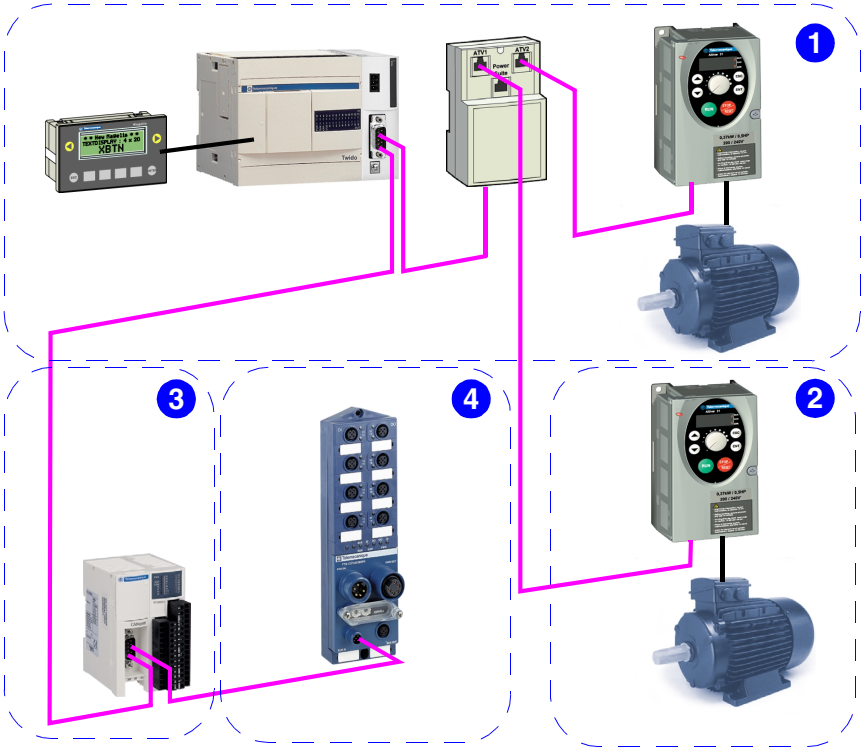
To control the system and give different kinds of information, we shall next add an Advantys OTB IP20 I/O module to the system as well as an Advantys FTB IP67 I/O splitter.

The automation solution includes the following elements:

| Element | Description |
|---|---|
| Twido Controller | The Twido controller associated with the CANopen master supports the following:<br>● management and communication of the CANopen slaves: the ATV31 variable speed controller and the I/S modules,<br>● diagnostics for the ATV31 variable speed controller and the I/S modules,<br>● management of the XBTN 400 operator display. |
| HMI | The XBTN 400 is used for the following:<br>● to display the system parameters: motor speed, information on the I/O, system diagnostics, etc.<br>● to change the system parameters: motor speed. |
| Variable controller | The ATV31 variable speed controller is used for the following:<br>● to manage motor Start / Stop mode,<br>● to change the motor speed. |
| I/O modules | The I/O modules provide the following:<br>● controller information to start/stop the motor,<br>● predefined motor speeds,<br>● information on the state of the system (led indicators). |

**Diagram of the Principal**

Here is the general diagram of the automation solution presented:




The present guide is divided into several sections depending on the modifications in the automation solution:

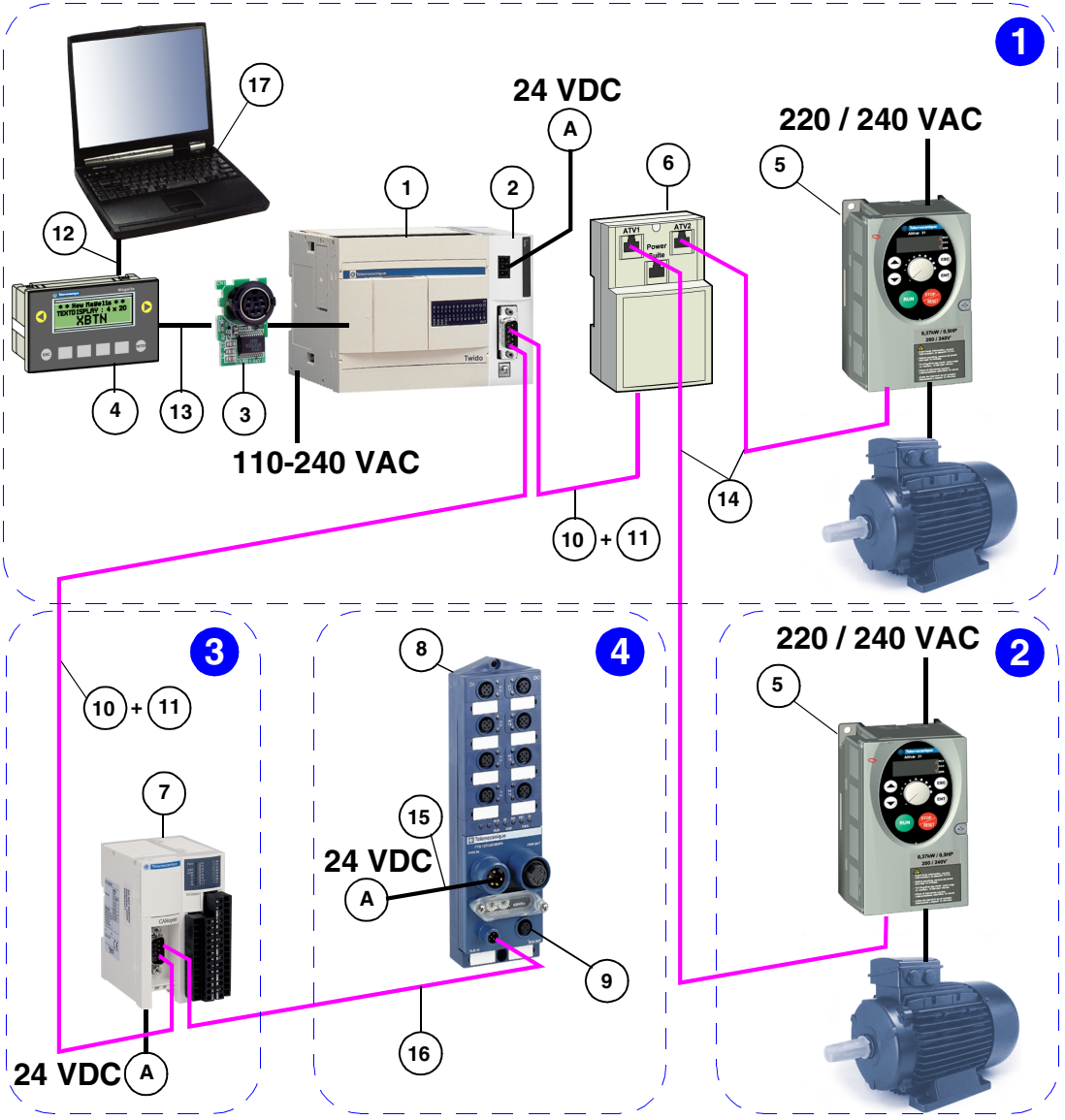
| Steps | Description |
|---|---|
| 1 | Main system |
| 2 | Addition of a second variable speed controller: ATV31 |
| 3 | Addition of a remote IP20 I/O module: Advantys OTB |
| 4 | Addition of a remote IP67 I/O splitter: Advantys FTB |

**Note:** If an application requires more products, check the corresponding user guides to see if they are compatible (for example: maximum number of elements managed by the Twido controller).

## Description

**Installation diagram**

The diagram below shows the automation solution:



## Required hardware

### Products

List of products:

| TYPE | Reference | Description | Quantity | Label |
|---|---|---|---|---|
| Controller | TWDLCAA24DRF | Compact Twido | 1 | 1 |
| Controller | TWDNCO1M | Twido CANopen master | 1 | 2 |
| Controller | TWDNAC485D | Optional mini DIN RS485 | 1 | 3 |
| HMI | XBTN400 | Compact display, 4 line, 20 character | 1 | 4 |
| Variable controller | ATV31H18Mxx | 0.18 kW/0.5 HP Monophase 200-240 V ATV31 | 1 | 5 |
| Accessories | VW3CANTAP2 | Derivation housing (TAP) | 1 | 6 |
| I/O | OTB1C0DM9LP | Advantys OTB CanOpen 12E 6S remote IP 20 I/O module | 1 | 7 |
| I/O | FTB1CN08E08SP0 | Advantys FTB CANopen 08E 08S remote IP67 I/O splitter | 1 | 8 |
| I/O | FTXCNTL12 | CanOpen M12 line end | 1 | 9 |

### Power supply and protection

List of recommended power supplies and protections

| Reference | Description | Quantity | Num. |
|---|---|---|---|
| ABL7RM2401 | Supply 24VDC | 1 | A |
| MULTI 9 -C10 | 20725 power breaker | 1 | - |

**Note:** Calibrate the power supply based on the application.

## Cables

List of cables:

| TYPE | Reference | Description | Quantity | Label |
|---|---|---|---|---|
| CANopen | TSXCANCA50 * | CANopen cable - bare wire 50 m | 1 | 10 |
| CANopen | TSXCANKCDF90T * | CANopen SUB-D 9 female connector with line end terminal | 2 | 11 |
| HMI | XBTZ945 | Configuration cable (PC - HMI) | 1 | 12 |
| HMI | XBTZ9780 | Link cable (HMI - Twido controller) | 1 | 13 |
| Variable controller | VW3CANCARR03 | 0.3 m CAN RJ45 cable for ATV31 | 1 | 14 |
| Variable controller | VW3CANCARR01 | 1 m CAN RJ45 cable for ATV31 | 1 | 14 |
| I/O | FTXDP2115 | 1 m Advantys FTB power cable | 1 | 15 |
| I/O | FTXCN3130 | 3 m M12 - free wire Advantys FTB power cable | 1 | 16 |
| I/O | FTXCN3150 | 5 m M12 - free wire Advantys FTB power cable | 1 | 16 |

* : or equivalent, reference available from 4th quarter 2005

## Software

List of programming and configuration software:

| TYPE | Reference | Description | Label |
|---|---|---|---|
| Controller | TWDSPU1004V10M | TwidoSoft ≥ V3.2 including a BlueTooth link* | 17 |
| HMI | XBTL1001M | XBTL1000 light ≥ V4.4 | |
| I/O | FTXES00 (≥ V3.0) | Advantys Configuration Tool ≥ V1.3 | |

* : If the PC is not Bluetooth equipped, obtain the USB key adaptor reference VW3A8115.

## Configuration

The present guide describes installation and implementation of the system, focusing on the main elements:

- A Twido TWDLCAA24DRF controller,
- An XBTN400 display,
- An ATV31H18Mxx variable speed controller,
- An Advantys OTB1C0DM9LP I/O module,
- An Advantys FTB1CN08E08SP0 I/O splitter,

# Main System

II

## At a Glance

**Overview**

This section of the document presents the installation of the main system.

**Objective**

The objective is to control an ATV31 variable speed controller via the CANopen bus using a Twido CANopen master. The XTBN allows to display / change the instruction of the speed controller and the I/O status information.

**Application files**

On the CD-ROM BUNDLE (DIA3CD3050101F), there are files for this configuration in the "Applicative files\Partie_II" folder for the Twido controller application and in the "Applicative files\XBTN_XBTR" folder for the XBTN operator display application.

**What's in this Part?**

This part contains the following chapters:


| Chapter | Chapter Name | Page |
|---|---|---|
| 2 | Hardware implementation of the main system | 23 |
| 3 | Software implementation of the main system | 31 |
| 4 | Presentation of the application | 37 |

# Hardware implementation of the main system

# 2

## At a Glance

**Overview**

This chapter describes hardware implementation of the main system of the automation solution.

**What's in this Chapter?**

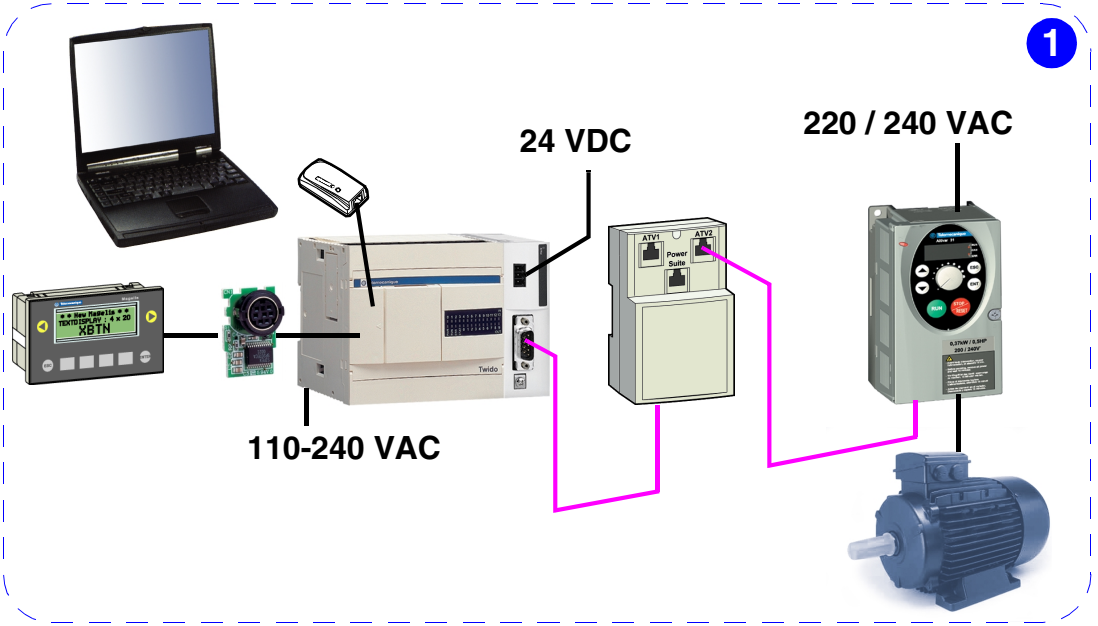
This chapter contains the following topics:


| Topic | Page |
|---|---|
| Main cabling | 24 |
| HMI cabling | 24 |
| CANopen network cabling | 25 |
| I/O cabling | 28 |
| Power supply | 30 |

## Main cabling

**Installation diagram**

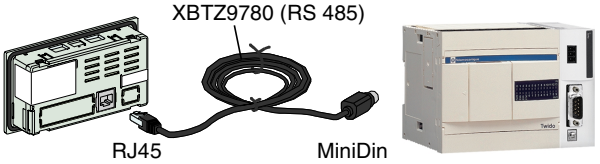
This part of the document covers the following mounting:




## HMI cabling

**XBTN-Twido cabling**

The link between the XBTN and the Twido controller is made with the XBTZ9780 cable:



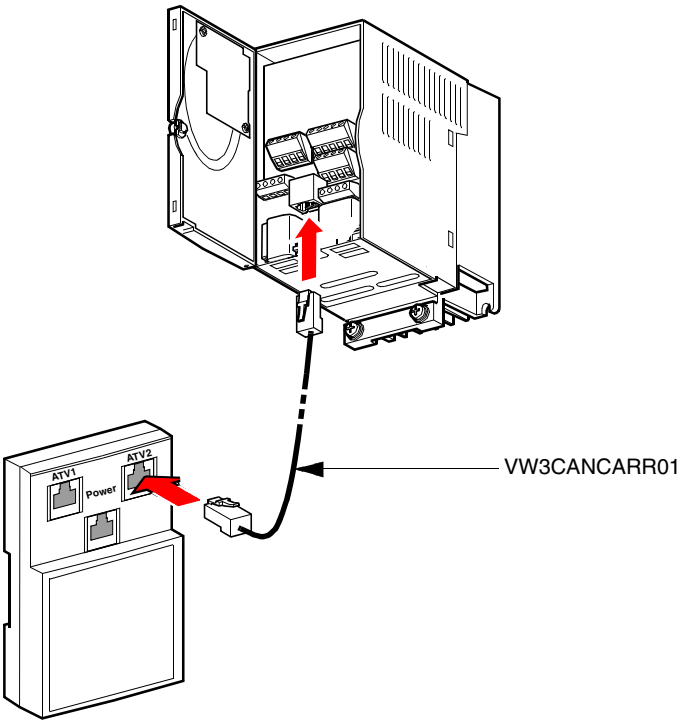

For easier use, use the additional interface mounted on the Twido controller.

For further information, see the Magelis XBTN / XBTR Operation Guide reference 1681028.

## CANopen network cabling

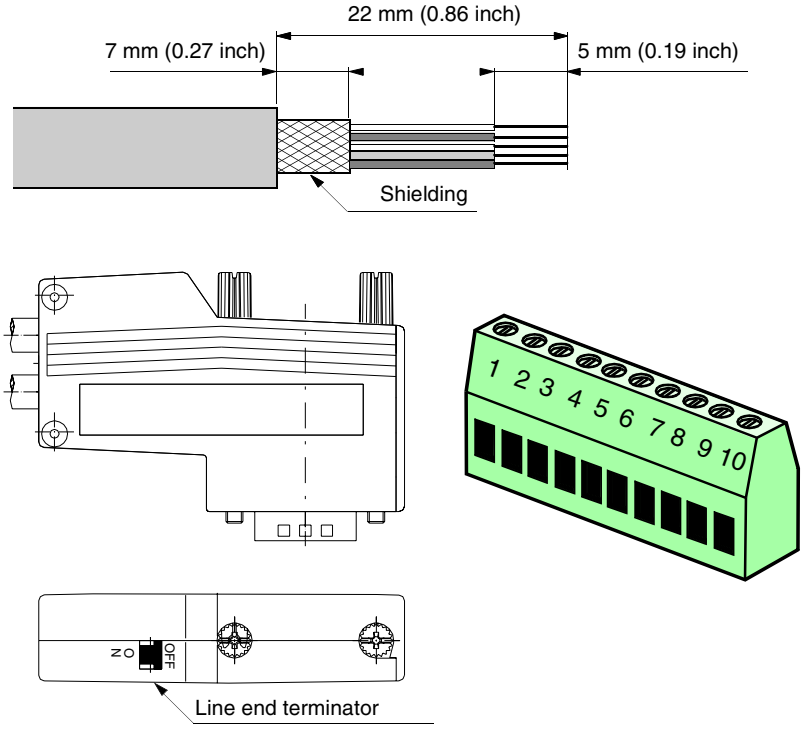
**ATV31-TAP Cabling**

To connect the ATV31 to the TAP, use the type RJ45 - RJ45 cable so that:



**TAP-Twido Cable Preparation**

To connect the TAP to the Twido controller, connect a SUB-D 9 TSXCANKCDF90T connector with the TSXCANCA50 cable in the following manner:



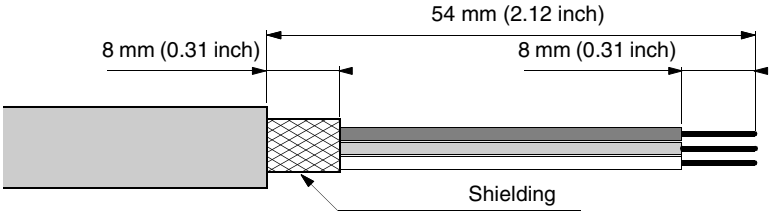

Cable pin assignment in the terminal of the SUB-D 9 connector:

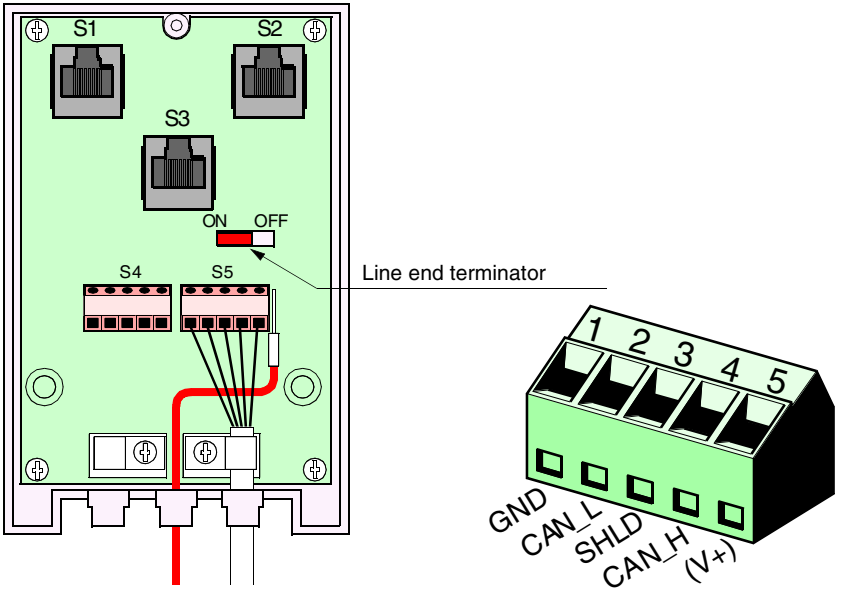
| Label | Signal | Cable | Wire color |
|---|---|---|---|
| 1 | V+ | TAP/Twido | Red |
| 2 | GND | TAP/Twido | Black |
| 3 | SHLD (CAN-GND) | TAP/Twido | (Bare cable shielding) |
| 4 | CAN_L | TAP/Twido | Blue |
| 5 | CAN_H | TAP/Twido | White |

**Note:** Toggle the line end terminator of the connector to "On".

**TAP-Twido cabling**

The SUB-D 9 end of the previously prepared cable is connected to the Twido controller. The "bare wire" end of the cable is connected in the TAP in the following manner:




Cable pin assignment in the TAP terminal:

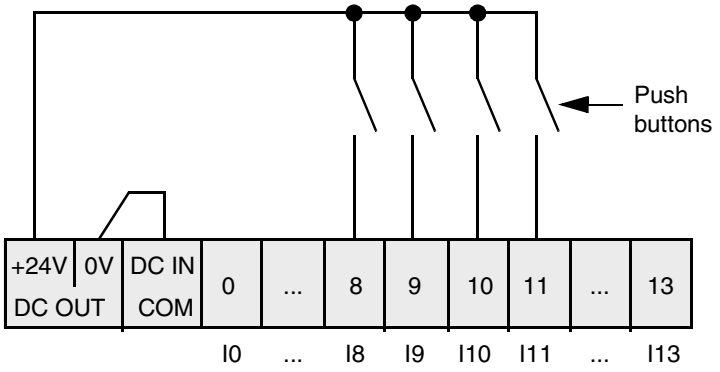
| Label | Signal | Wire color | Description |
|---|---|---|---|
| 1 | GND | Black | Weight |
| 2 | CAN_L | Blue | CAN_L polarity |
| 3 | SHLD (CAN-GND) | (Bare cable shielding) | Optional shielding |
| 4 | CAN_H | White | CAN_H polarity |
| 5 | (V+) | Red | Optional power supply (1) |

**Note:** Toggle the line end terminator of the TAP to "On".

## I/O cabling

### Twido inputs cabling

Diagram of inputs cabling:

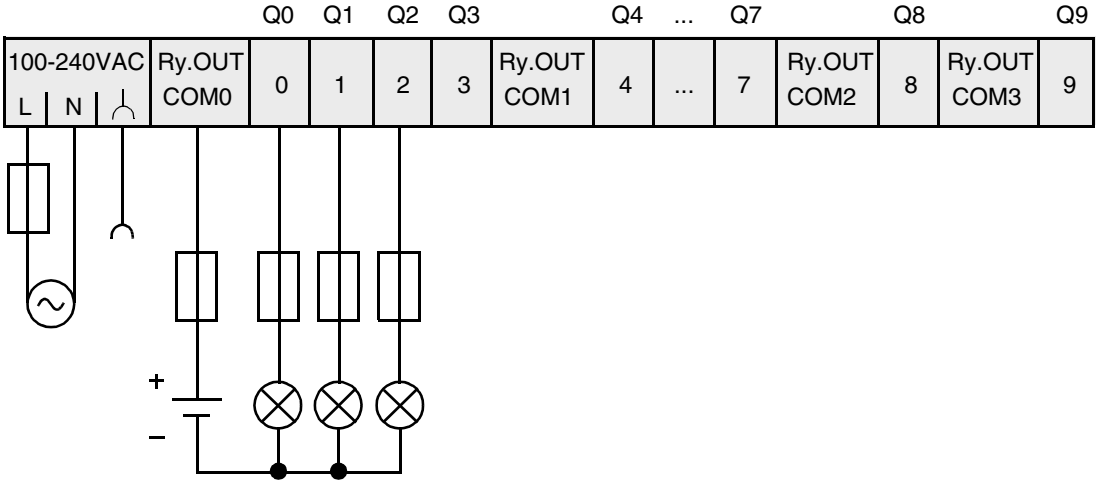



Additional information on inputs used in the application:

| Input | Symbol used in the Twido application | Action |
|---|---|---|
| %I0.8 | PB_START_FORWARD | Start forward motor rotation |
| %I0.9 | PB_START_REVERSE | Start reverse motor rotation |
| %I0.10 | PB_STOP | Stop motor |
| %I0.11 | PB_SLOW_FAST | Set speed fast or slow:<br>● Input = 1 for fast<br>● Input = 0 for slow |

**Twido outputs cabling**

Diagram of outputs cabling:




Additional information on outputs:

| Output | Symbol used in the Twido application | Indication displayed |
|---|---|---|
| %Q0.0 | SD_RUN_FORW | Forward motor rotation |
| %Q0.1 | SD_RUN_REV | Reverse motor rotation |
| %Q0.2 | SD_STOPPED | Motor stopped |

## Power supply

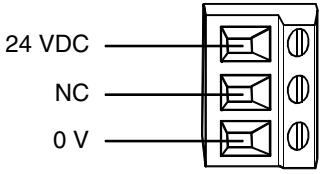
**Power on the Twido**

To power on the Twido controller, follow the recommendations provided in the "Hardware implementation guide."

**Power on the CAN Master**

To power on the CANopen master, follow the recommendations in the Service Instructions provided with the product.

Cabling Diagram:




**Power on the ATV31**

**⚠ DANGER**

To power on the ATV31 variable speed controller, follow the recommendations provided in the Installation Guide ref. VVDED303043.
**Failure to follow this instruction will result in death or serious injury.**

# Software implementation of the main system

# 3

## At a Glance

**Overview**

This chapter describes software implementation of the main system of the automation solution.

**What's in this Chapter?**

This chapter contains the following topics:


| Topic | Page |
|---|---|
| Installing Software and Loading Applications | 32 |
| ATV31 communications configuration | 35 |

## Installing Software and Loading Applications

**applications**

The CD-ROM BUNDLE (DIA3CD3050101F) contains the Applications files corresponding to the automation solution. Loading these files will allow a simple startup for the automation solution.

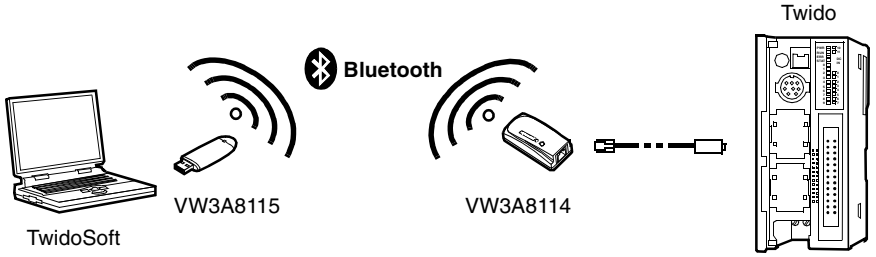
**Software Installation**

It is necessary, at the start, to install the following software:

- An XBT-L1000 for the XBTN operator display
- TwidoSoft for the Twido controller

**Twido Application**

Connect the Twido controller to a PC in the following manner:



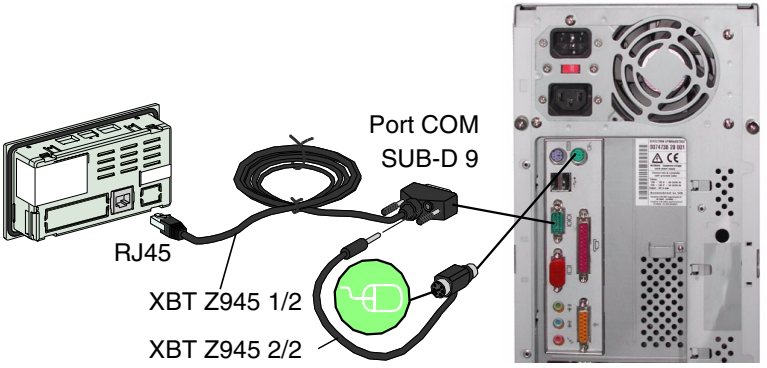

**Note:** It is recommended to add an RS485 additional interface to the Twido controller. This will allow the PC to be connected to the Twido controller without having to unplug the XBTN operator display.

The following method allows to load the application provided for the Twido controller:

| Step | Action |
|---|---|
| 1 | From the CD-ROM BUNDLE (DIA3CD3050101F), **COPY** the file "Partie II\QUICK_START_TWIDO_CAN part II conf1 v1_1.TWD" |
| 2 | **PASTE** this file into the directory "C:\Program Files\Schneider Electric\TwidoSoft\Applications" |
| 3 | Open the file using TwidoSoft software. |
| 4 | Connect the Twido controller to the PC (see above diagram). The controller must be powered on. |
| 5 | From the Twido software menu bar, select "Controller/Connect...":<br>● If the firmware of the Twido controller is not up-to-date, the following message will appear: "The controller firmware (2.XX) is not compatible with the generated application." Select "Tools/Update PLC microprogram" to launch the update. In step 2/4, click on "Browse" to select, on the TwidoSoft CD-ROM, the "Firmware\X.XX\"TWIDOYYY_V0XXXP00.tfw" file for the controller XXX that corresponds to the firmware version (XXX ≥ 3.2).<br>● If the applications of the PC and the controller are different, a window will appear. Click on the "PC => Controller" button to start loading the program in the Twido controller. |
| 6 | Wait until the program is finished loading.<br>From the TwidoSoft menu, select "Controller/Disconnect". |

**XBTN**

To connect the XTBN to a PC, use the XBTZ945 cable:




For further information, see the Magelis XBTN / XBTR Operation Guide reference 1681028.

The following method allows to load the program provided for the XBTN:

| Step | Action |
|---|---|
| 1 | From the CD-ROM BUNDLE (DIA3CD3050101F), **COPY** the file "XBTN_XBTR\QS_XBT_N400.DOP" |
| 2 | **PASTE** this file into the directory "C:\Program Files\Schneider Electric\XBT-L1000\appli" |
| 3 | Open the file using the XBT-L1000 software. |
| 4 | Connect the XBTN operator display to the PC (see above diagram). The XBTN operator display must be powered on (for more information, see the operation guide of the operator display.<br>The XBTN displays "WAITING FOR TRANSFER". |
| 5 | From the XBT-L1000 software menu bar, select "Transfer/Export". |
| 6 | Wait until the program is finished loading to disconnect the XTBN from the PC. |

## ATV31 communications configuration

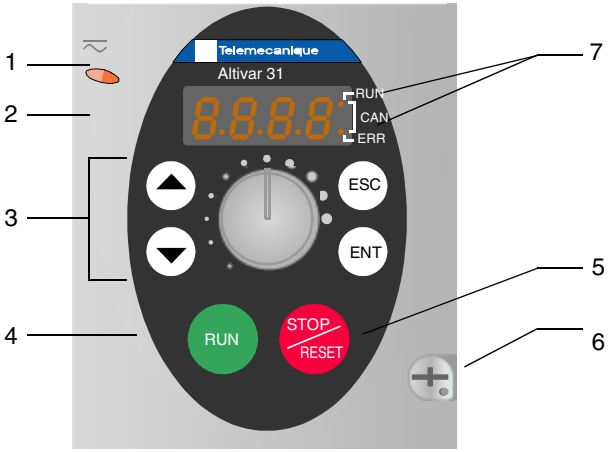
**Principle**

The system products must be configured according to the Twido application controller as follows:

- Address 1: ATV31
- Transmission Speed: 125 kBits/s

**Description**

Front panel of the ATV31 variable speed controller:




| No. | Description |
|---|---|
| 1 | The red LED on indicates that the direct bus is powered on. |
| 2 | 4-digit "7 segments" operations display. |
| 3 | Central programming terminal. |
| 4 | "RUN" key, for starting motor in forward mode. |
| 5 | "STOP/RESET" key, for stopping the motor and resetting the current defaults. |
| 6 | To lock/unlock the front panel of the speed controller, a flat or cross-slot screwdriver is needed. |
| 7 | These two LEDs indicate the status of communications ("RUN") and the presence of a possible fault ("ERR") on the CANopen bus. |

**Method**

Configuration of ATV31 communication parameters:

| Step | Action |
|---|---|
| 1 | Press on the "ENT" key to enter the ATV31 configuration menu. |
| 2 | Use the "Arrows" keys to select the "COM" Communication menu then confirm using the "ENT" key. |
| 3 | Use the "Arrows" keys to select the "AdCO" menu then confirm using the "ENT" key.<br>Enter the value "1" (Address on the CANopen bus).<br>Confirm using the "ENT" key then exit the menu using the "ESC" key. |
| 4 | Use the "Arrows" keys to select the "bdCO" menu then confirm using the "ENT" key.<br>Enter the value "125" (Speed on the CANopen bus).<br>Confirm using the "ENT" key then exit the menu using the "ESC" key. |
| 5 | Use the "ESC" key to exit the configuration menu. |

**Note:** The configuration may be modified only when the motor is stopped and when the variable speed controller is locked (cover closed). Any modification entered will become effective after an "Off/On" cycle of the speed controller.
For more information, see the reference document VVDED303042.

**Special Note**

In the event of use WITHOUT MOTOR (simulation mode), the ATV31 variable speed controller will display an error message: "OPF". Change the configuration in the "FLt / OPL" submenu and send the value "YES" to "OAC".

**Communication Parameters**

Use the "COM" communication menu to access configuration of CANopen communication functions of the ATV31 connected to a Twido controller:

| Parameter | Possible Values | Display on terminal | Values to input for the application |
|---|---|---|---|
| CANopen AdC0 address | 0 to 15 | 1 to 16 | 1 |
| CANopen bdC0 speed | 125 kBits/s | 125.0 | 125 kBits/s |
| | 250 kBits/s | 250.0 | |
| | 500 kBits/s | 500.0 | |

# Presentation of the application

# 4

## Operating mode

**Commands**

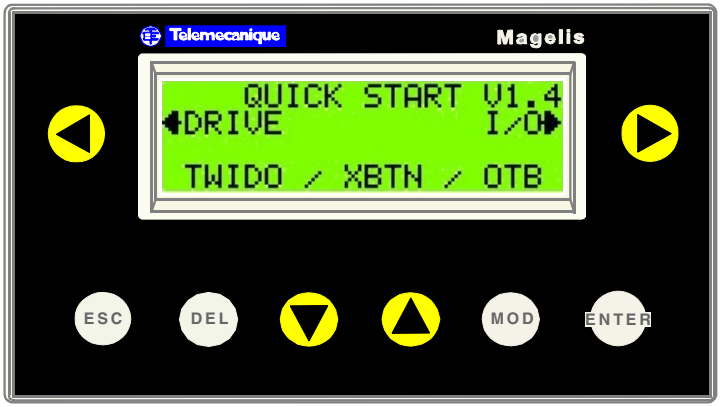
When system installation is complete, the system may be controlled using three push buttons and one two-position button.

| **Input**<br>**Corresponding symbol** | **Function** | **Description** | **Output**<br>**Corresponding symbol** |
|---|---|---|---|
| %I0.8<br>PB_START_FORWARD | Forward start | The corresponding LED turns on when the selected speed is reached. | %Q0.0<br>SD_RUN_FORW |
| %I0.9<br>PB_START_REVERSE | Reverse start | The corresponding LED turns on when the selected speed is reached. | %Q0.1<br>SD_RUN_REV |
| %I0.10<br>PB_STOP | Stop motor | The corresponding LED turns on when the motor stops. | %Q0.2<br>SD_STOPPED |
| %I0.11<br>PB_SLOW_FAST | Predefined motor speeds | Apply a predefined speed when changing position:<br>• %I0.11 is set to 1: 3300 tr/min<br>• %I0.11 is set to 0: 88 tr/min | No output to match input |

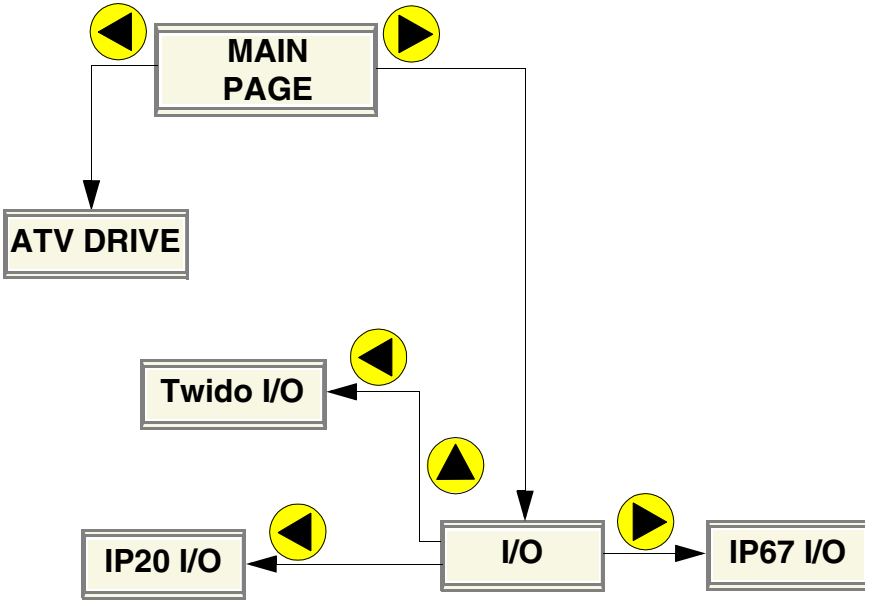
**Note:** In our sample application, the push button for %I0.10 must be pushed (Stop motor) in order to change the direction of motor rotation.

**HMI**

**XBTN main page:**




**Organigram of XBTN pages:**




**Note:** Press on the ESC key to return to the preceding page.

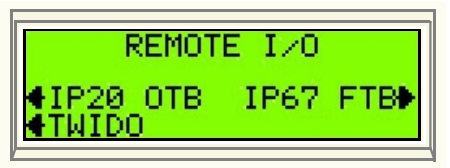
**XBTN "ATV DRIVE" page:**

The "ATV DRIVE" page displays the speed instruction sent to the ATV31 by the Twido controller.

To modify speed, do the following:

| Step | Action |
|---|---|
| 1 | Press on the MOD key. |
| 2 | Use the ▲ and ▼ arrows to change the speed (immediate write). |
| 3 | Press on the ENTER key to confirm. |

**XBTN "I/O" page:**




The "I/O" screen provides access to 3 screens that display the status of:

- I/O of the Twido controller,
- I/O of the Advantys OTB I/O module (see *Add an Advantys OTB I/O module, p. 57*),
- I/O of the Advantys FTB I/O splitter (see *Add an Advantys FTB I/O splitter, p. 83*).

# Add a second ATV31 variable speed controller

III

## At a Glance

**Overview**

This section of the document presents a possible evolution of the main system, that is the addition of a second ATV31 speed controller.

These two speed controllers function in exactly the same manner.

**Application files**

Files for this configuration may be found on the CD-ROM BUNDLE (DIA3CD3050101F) in the "Applicative files\Partie_III" folder for the Twido controller application.

**What's in this Part?**

This part contains the following chapters:


| Chapter | Chapter Name | Page |
|---|---|---|
| 5 | Hardware implementation of a second ATV31 speed controller | 43 |
| 6 | Software implementation of a second ATV31 speed controller | 47 |

# Hardware implementation of a second ATV31 speed controller

# 5

## At a Glance

**Overview**

This chapter describes hardware implementation of a second ATV31 variable speed controller.

**What's in this Chapter?**

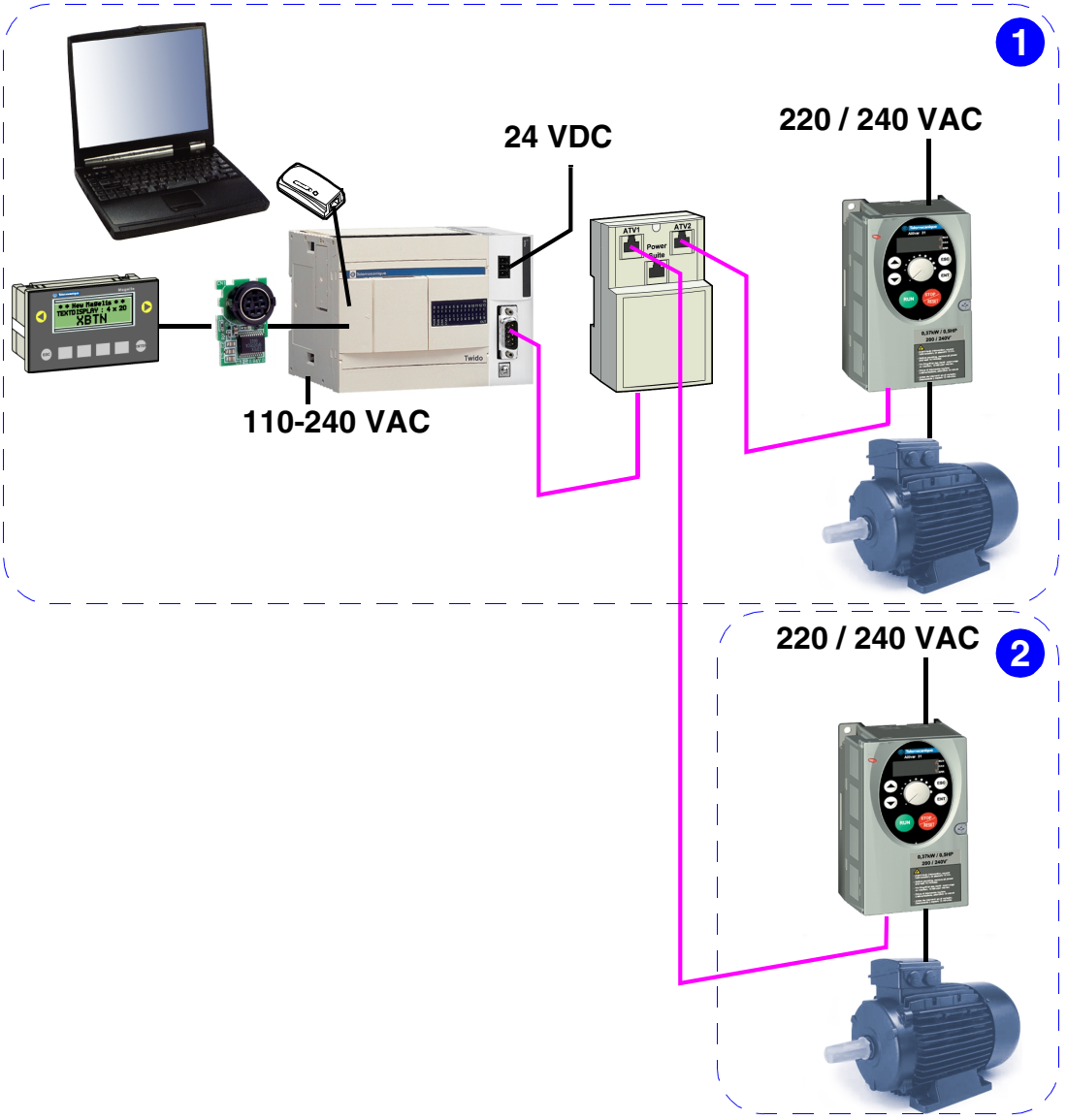
This chapter contains the following topics:


| Topic | Page |
|---|---|
| Second ATV31 cabling | 44 |
| Cabling of the CANopen network | 45 |
| Power supply | 46 |

## Second ATV31 cabling

**Installation diagram**

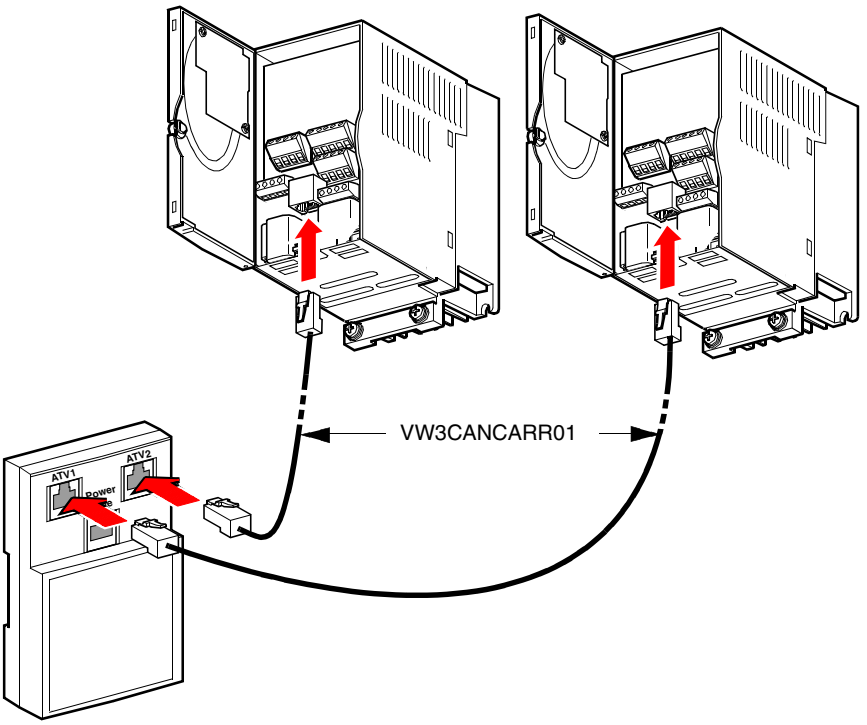
This part of the document covers the following mounting:



## Cabling of the CANopen network

**ATV31-TAP Cabling**

To connect the ATV31 to the TAP, use the type RJ45 - RJ45 cable so that:



## Power supply

### Power on the ATV31

**⚠ DANGER**

To power on the ATV31 variable speed controller, follow the recommendations provided in its Installation Guide reference VVDED303043.
**Failure to follow this instruction will result in death or serious injury.**

# Software implementation of a second ATV31 speed controller

# 6

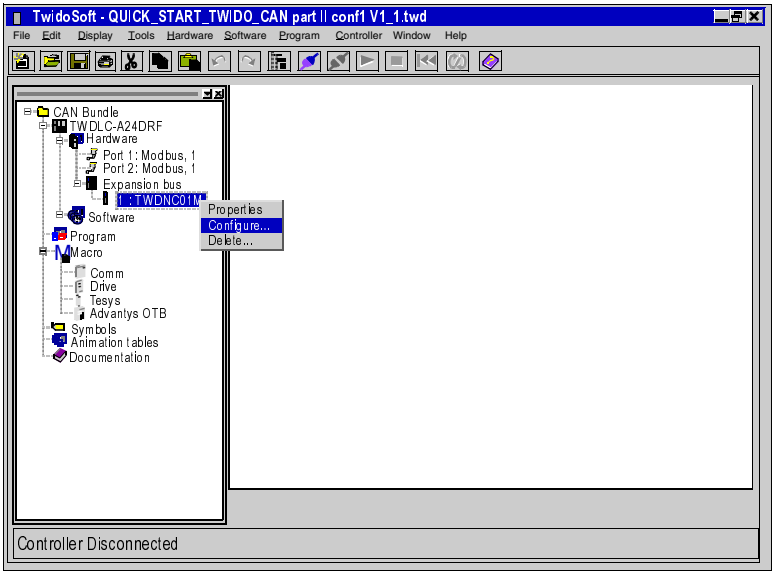
## Add a second ATV31 in the Twido controller application

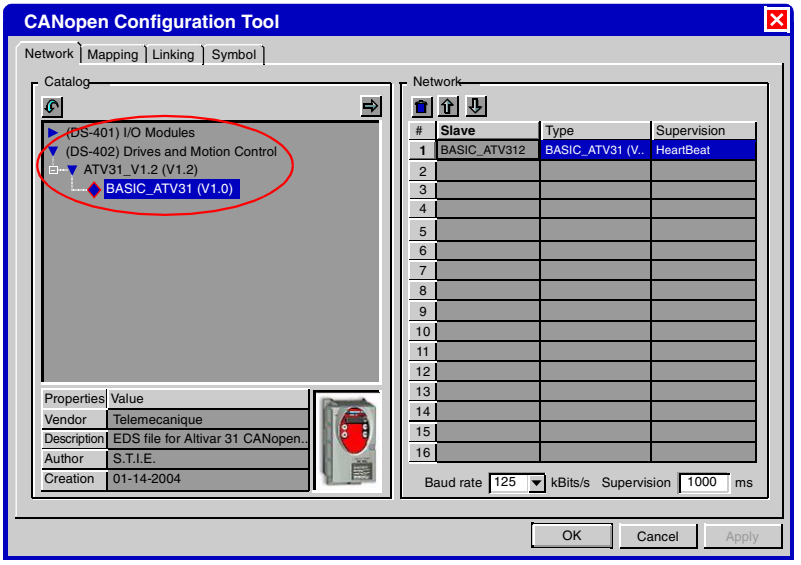
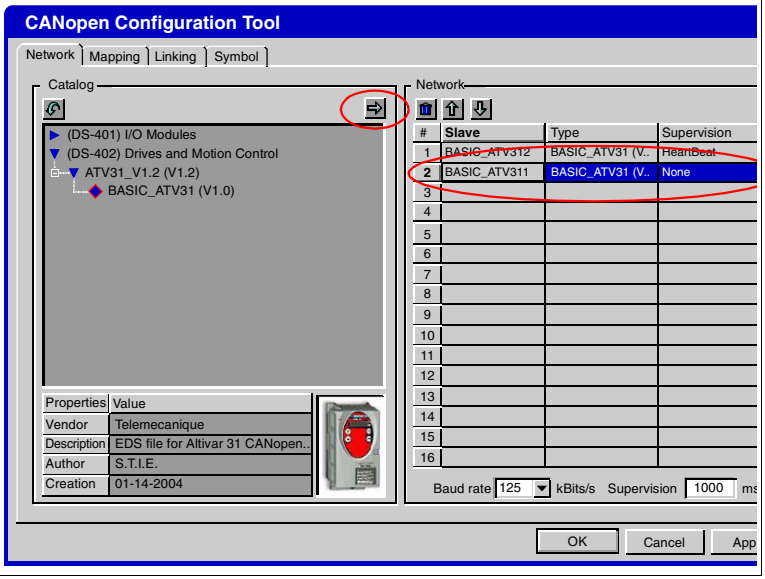
**Principle**

The object is to modify the existing application in order to be able to control the second ATV31 the same as the first ATV31.

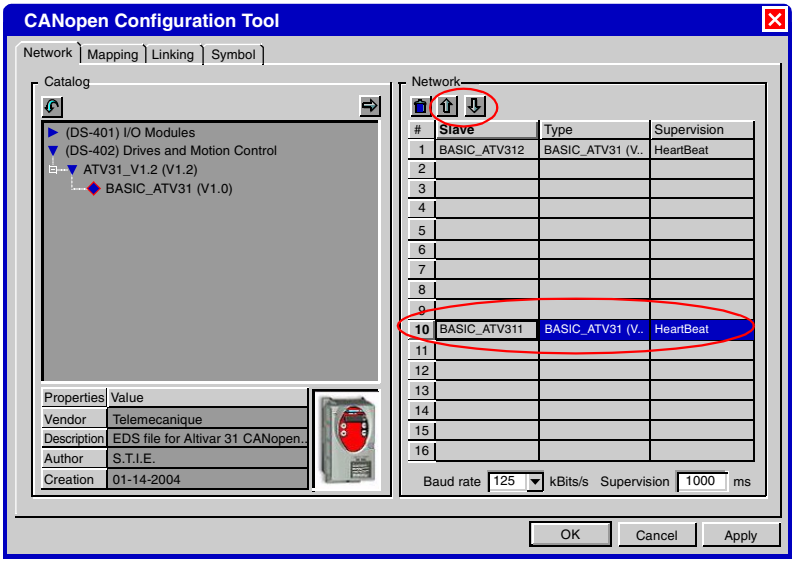
**Declare the second ATV31**

The following method allows declaration of the second ATV31 variable speed controller in the Twido controller and in the CANopen master.

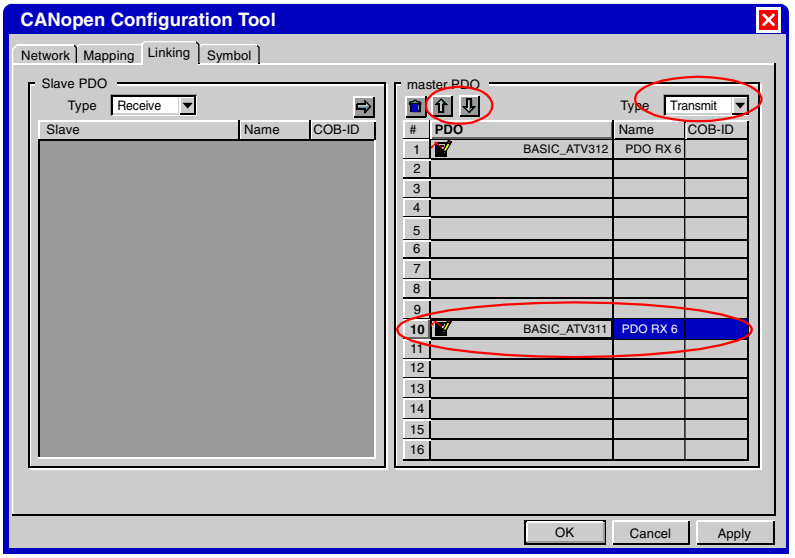
| Step | Action |
|---|---|
| 1 | Open the application "BUNDLE\Partie_II\QUICK_START_TWIDO_CAN part II conf1 v1_1.TWD" using the TwidoSoft software (TwidoSoft must be in disconnected mode). Right click on the expansion bus and select "Configure".   |

| Step | Action |
|---|---|
| 2 | Expand the tree of the Drives and Motion Control (DS-402) profile:   |
| 3 | Select "BASIC_ATV31 (V1.0)" in the "Catalog" area and click on ⇨ to add the new ATV31 speed controller in the Network area.   |

| Step | Action |
|---|---|
| 4 | Click on to declare the new speed controller at the network address 10: |

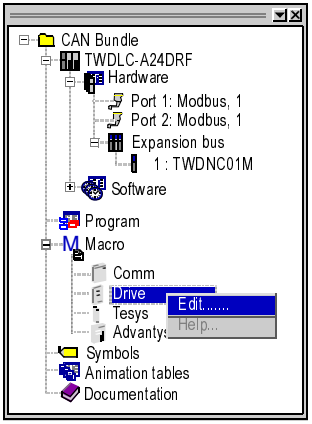
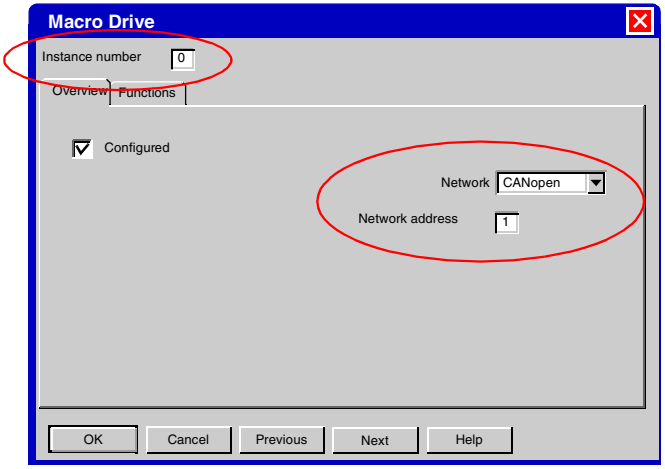


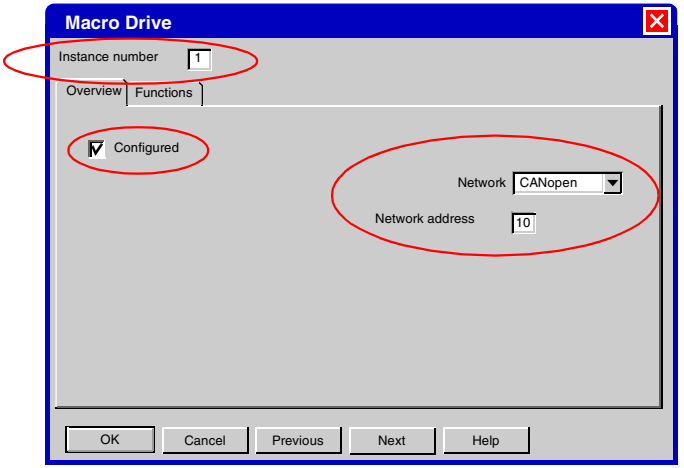
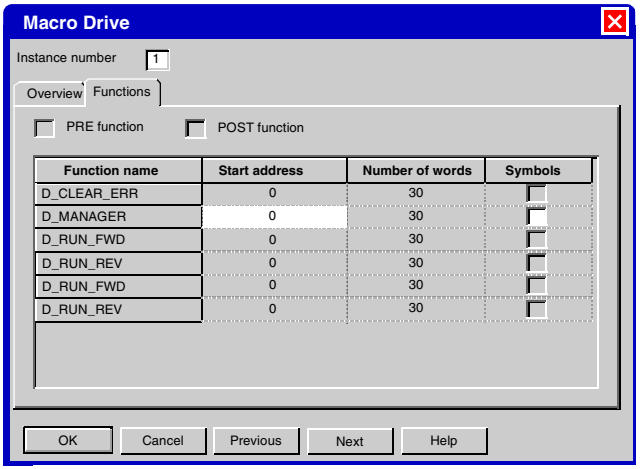

**Important note**: The Supervision type stays on "None", the motor will continue to turn even if the communication between the CANopen bus and the ATV31 is interrupted. **Change the Heartbeat value**.

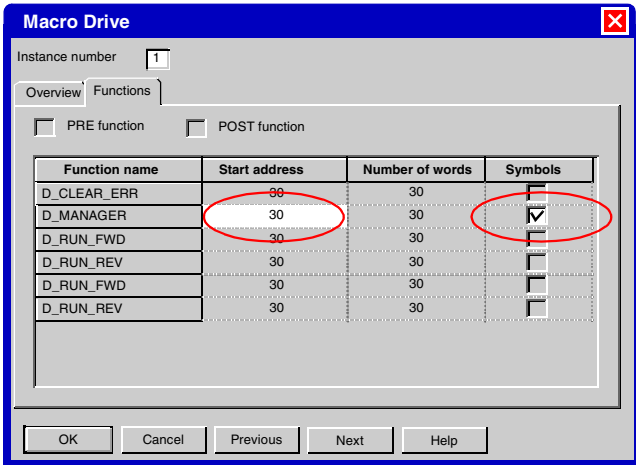
| Step | Action |
|---|---|
| 5 | Select the "Linking" tab.<br>Use ⇨ and ⇩ to assign the new speed controller to the PDO number 10, both in "Receive" and "Send":<br>  <br> |
| 6 | Click on the "OK" button to confirm. The new speed controller is then declared in the Twido controller and in the CANopen master. |

## Macro Drive of the second ATV31

The following method allows configuration of the second ATV31 variable speed controller in the Macro Drive of the application in order to be able to control it.

| Step | Action |
|---|---|
| 1 | Right click on "Macro/Drive" and select "Edit".   |
| 2 | The Macro Drive window appears:   The first ATV31 speed controller is declared in the Macro Drive under number no. 0. It can be seen that its CANopen network address is indeed 1. |

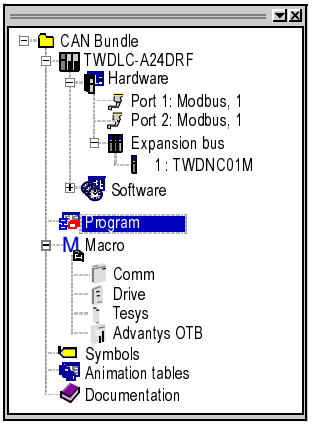
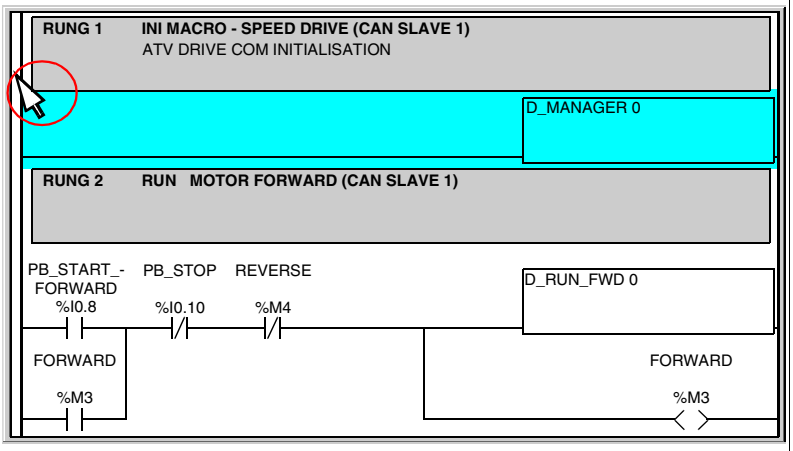
| Step | Action |
|---|---|
| 3 | Click on the "Next" button to display instance no. 1.<br>Check the "Configure" box.<br>Set the CANopen network address to 10.<br>  <br> |
| 4 | Click on the "Functions" tab.<br>  <br> |

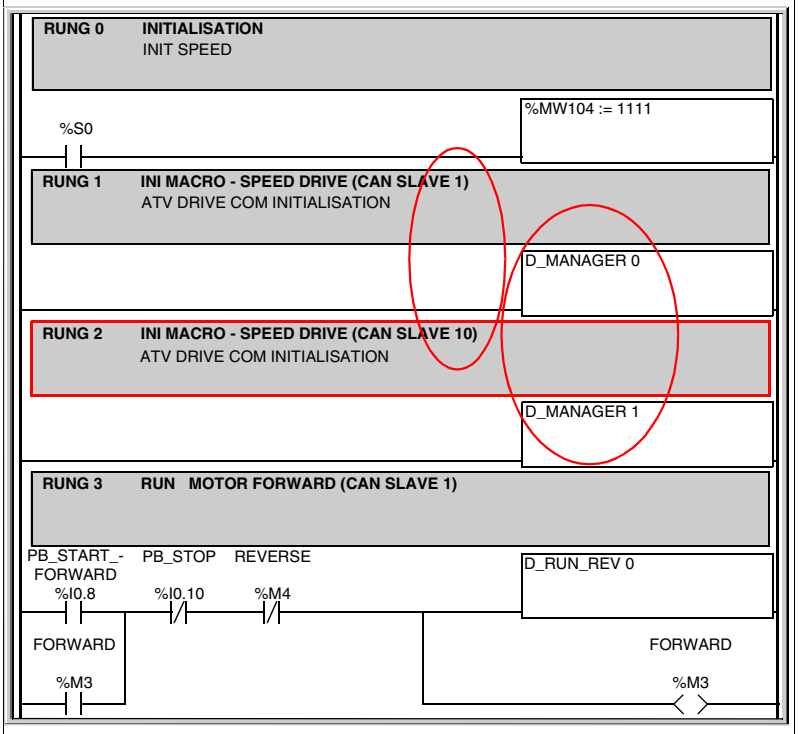
| Step | Action |
|---|---|
| 5 | Click in the white area (Beginning address) and enter the value 30.<br>Check the "Symbols" box:<br>  <br><br>**Note**: Instance no. 1 (first ATV31) uses 30 words starting at address 0; i.e. words %MW0 to %MW29. Instance no. 1 should have a different address range. Instance no. 1 uses words %MW30 to %MW59. |
| 6 | Click on the "OK" button to confirm. |

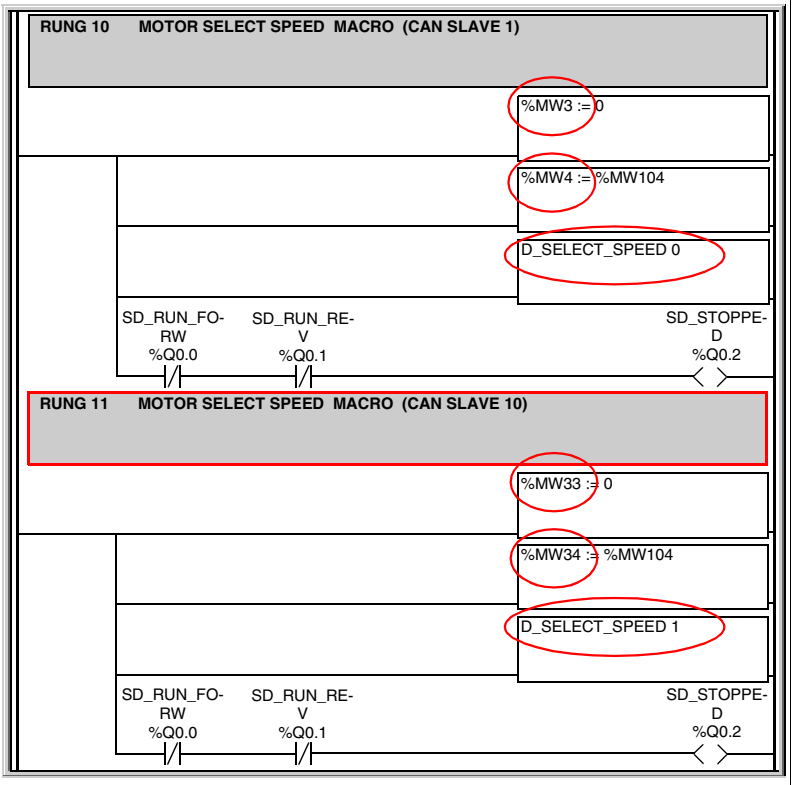
**Non-reversible**

The following method allows modification of the application to control of the second ATV31 variable speed controller.

The method involves Copy/Paste operations of all the lines that allow control of the first ATV speed controller then changing them to control the second speed controller in the same way.

| Step | Action |
|---|---|
| 1 | Double click on "Program" to open the programming window:   |
| 2 | Click on the left side of the line "RUNG 1" to select the whole line. The selected line turns blue:   |
| 3 | Copy the line: "Edit / Copy" or "Ctrl+C".<br>Select the new line ("RUNG 2" for example).<br>Paste the new line: "Edit / Paste" or "Ctrl+V". |

| Step | Action |
|---|---|
| 4 | Select the new line.<br>Double click on the function "D_MANAGER_0" and change it to "D_MANAGER_1" in order to match the instance no. of the second ATV31. Confirm this modification with the "ENTER" key on the keyboard.<br>Click on the line header to change the comment. Next click on the "OK" button to confirm.<br>  <br><br>The first line allowing to control the second ATV31 is created. |

| Step | Action |
|---|---|
| 5 | Redo steps 2 to 4 so that all lines include the following functions:<br>● D_CLEAR_ERR<br>● D_RUN_FWD<br>● D_RUN_REV<br>● D_STOP<br>● D_SELECT_SPEED<br>On each new line, the words %MW0 to %MW29 relating to the first ATV31 should also be modified respectively as %MW30 to %MW59 (See *Macro Drive of the second ATV31, p. 51*).<br>Here is the example of managing the speed of the motors:<br>  <br> |
| 6 | Perform a "File / Save". |
| 7 | Load the new application into the Twido controller: Perform a "Controller/Connect" and click on the "PC -> Automate" button. |

# Add an Advantys OTB I/O module

# IV

## At a Glance

**Overview**

This section of the document presents a possible evolution of the main system, that is the addition of an Advantys OTB I/O module.

**Note:** If you are not using a speed controller in your application, erase the associated elements in the CANopen configuration as well as in the Twido controller application program.

**Application principle**

The following example will allow to control outputs of the Advantys OTB I/O module the same as those of the Twido controller.

**Files**

Files for this configuration may be found on the CD-ROM BUNDLE (DIA3CD3050101F) in the "Applicative files\Partie_IV" folder for the Twido controller application.

**What's in this Part?**

This part contains the following chapters:


| Chapter | Chapter Name | Page |
|---|---|---|
| 7 | Hardware implementation of an Advantys OTB module | 59 |
| 8 | Software implementation of an Advantys OTB module | 63 |
| 9 | Add expansion modules to the Advantys OTB | 75 |

# Hardware implementation of an Advantys OTB module

# 7

## At a Glance

**Overview**

This chapter describes hardware implementation of an Advantys OTB I/O module added to the main system.

**What's in this Chapter?**

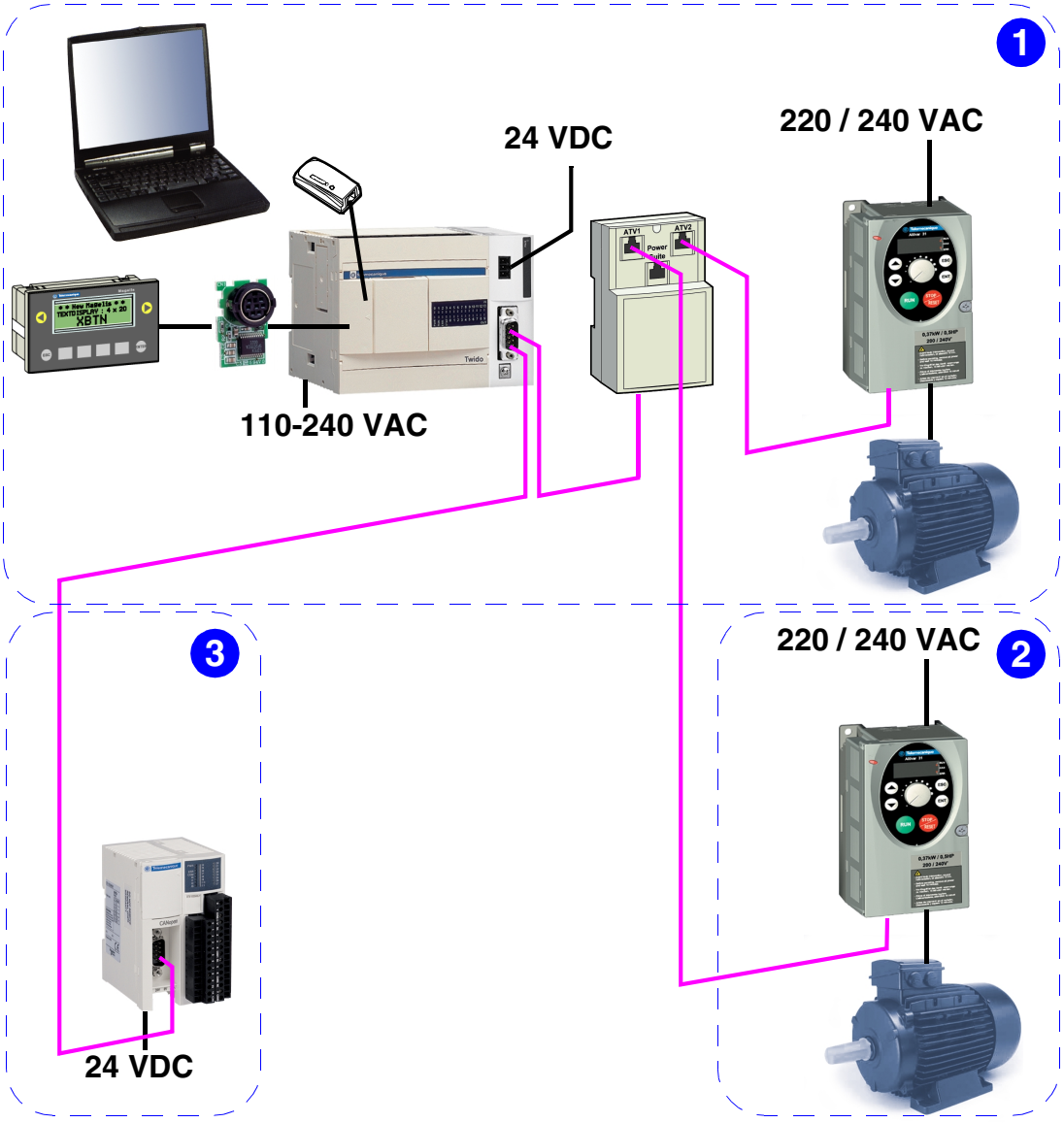
This chapter contains the following topics:


| Topic | Page |
|---|---|
| Advantys OTB outputs cabling | 60 |
| Cabling of the CANopen network | 61 |
| Advantys OTB I/O cabling | 62 |
| Power supply | 62 |

## Advantys OTB outputs cabling

**Installation diagram**

This part of the document covers the following mounting:



## Cabling of the CANopen network

**Principle**

The objective is to connect the Advantys OTB to the Twido controller using a cable that first must be prepared.

**OTB-Twido cable preparation**

Connect a SUB-D 9 TSXCANKCDF90T connector with the TSXCANCA50 cable (see *TAP-Twido Cable Preparation, p. 26*).

Cable pin assignment in the terminal of the SUB-D 9 connector:

| No. | Signal | Cable | Wire color |
|---|---|---|---|
| 1 | V+ | OTB/Twido | Red |
| 2 | GND | OTB/Twido | Black |
| 3 | SHLD (CAN-GND) | OTB/Twido | (Bare cable shielding) |
| 4 | CAN_L | OTB/Twido | Blue |
| 5 | CAN_H | OTB/Twido | White |

**Note:** Toggle the line end terminator of the connector on the Advantys OTB side to "On".

**OTB side cabling**

The SUB-D 9 end of the previously prepared cable is connected to the Advantys OTB.

**Twido side cabling**

The "bare wire" end of the previously prepared cable is connected to the SUB-D 9 connector joined to the Twido controller. This mounting is performed in the same manner as previously with the following pin assignment:

| No. | Signal | Cable | Wire color |
|---|---|---|---|
| 6 | CAN_L | OTB/Twido | Blue |
| 7 | CAN_H | OTB/Twido | White |
| 8 | SHLD (CAN-GND) | OTB/Twido | (Bare cable shielding) |
| 9 | V+ | OTB/Twido | Red |
| 10 | V+GND | OTB/Twido | Black |

**Note:** Toggle the line end terminator of the SUB-D 9 connector on the Twido controller side to "Off".

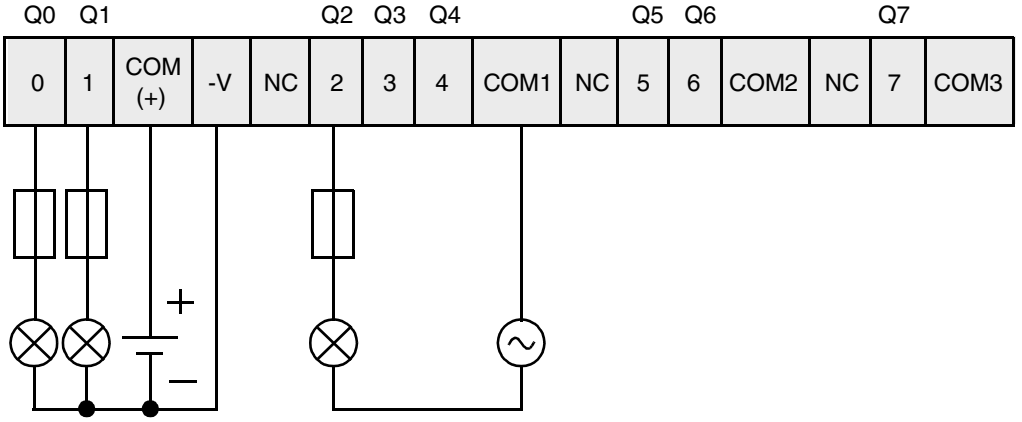
## Advantys OTB I/O cabling

**OTB inputs cabling**

Inputs of the Advantys OTB I/O module are not used in this example. For more information, see the reference guide 160384.

**OTB outputs cabling**

Diagram of outputs cabling:




Additional information on outputs:

| Output | Indication displayed | Information |
|---|---|---|
| %QWC1.1.0:X0 | Forward motor rotation | Source output |
| %QWC1.1.0:X1 | Reverse motor rotation | Source output |
| %QWC1.1.0:X2 | Motor stopped | Relay output |

## Power supply

**Power on the Advantys OTB**

To power on the Advantys OTB I/O module, follow the recommendations provided in reference guide 1606384.

# Software implementation of an Advantys OTB module

# 8

## At a Glance

**Overview**

This chapter describes software implementation of an Advantys OTB I/O module added to the main system.

**What's in this Chapter?**

This chapter contains the following topics:


| Topic | Page |
|---|---|
| Configuration of Advantys OTB communications | 64 |
| Add an Advantys OTB module in the Twido controller application | 66 |

## Configuration of Advantys OTB communications

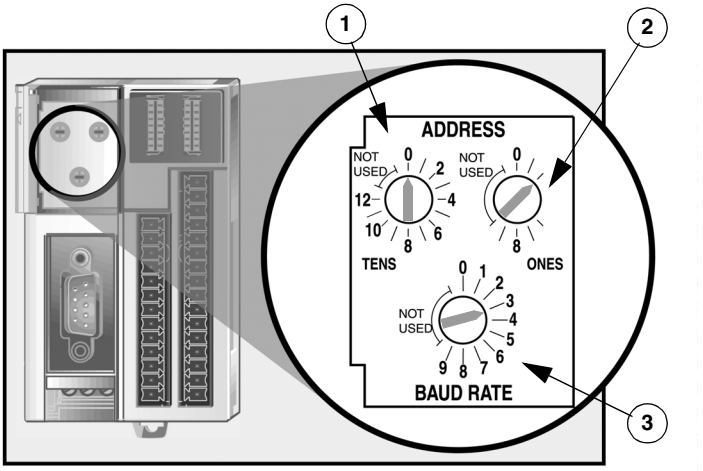
**Principle**

The system products must be configured according to the Twido application controller as follows:

- Address 1: ATV31
- Address 2: Advantys OTB
- Address 10: second ATV31
- Transmission Speed: 125 kBits/s

**Description**

Front panel of the Advantys OTB I/O module:




| No. | Function |
|---|---|
| 1 | Network address (Node-ID x10) encoder wheel |
| 2 | Network address (Node-ID x1) encoder wheel |
| 3 | Transmission speed encoder wheel |

**Method**

Configuration of Advantys OTB communication parameters:

| Step | Action |
|---|---|
| 1 | Cut off all power to the Advantys OTB. |
| 2 | Set the lower encoder wheel 3 to the position corresponding to the required baud rate.<br>In the example: encoder wheel 3 is set to position 3 (125 kBits/s). |
| 3 | Set encoder wheels 1 and 2 to the position corresponding to the desired network address. In the example, the address is 2 (10x0 + 1x2):<br>● encoder wheel 1: position 0 (tens)<br>● encoder wheel 2: position 2 (units) |
| 4 | Reapply power to the OTB in order to implement the new configuration. |

**Note:** After changing any features of the components of the CANopen network, the bus should be reinitialized by cycling the Twido controller On/Off.

## Add an Advantys OTB module in the Twido controller application

**Principle**

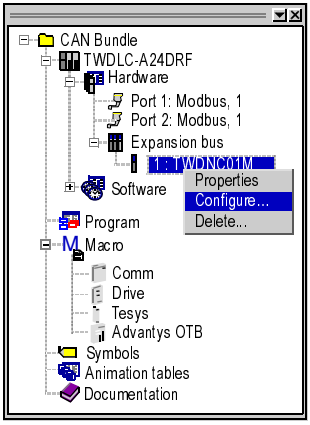
The objective is to modify the existing application in order to be able to manage the I/O of the Advantys OTB module.

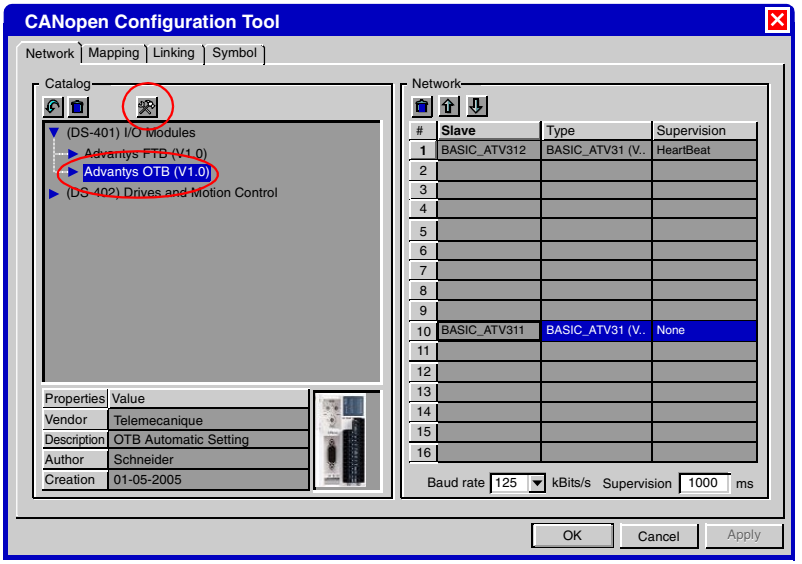
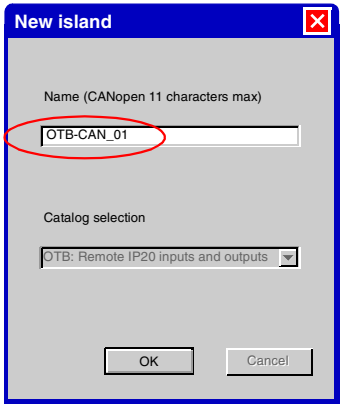
**Software Installation**

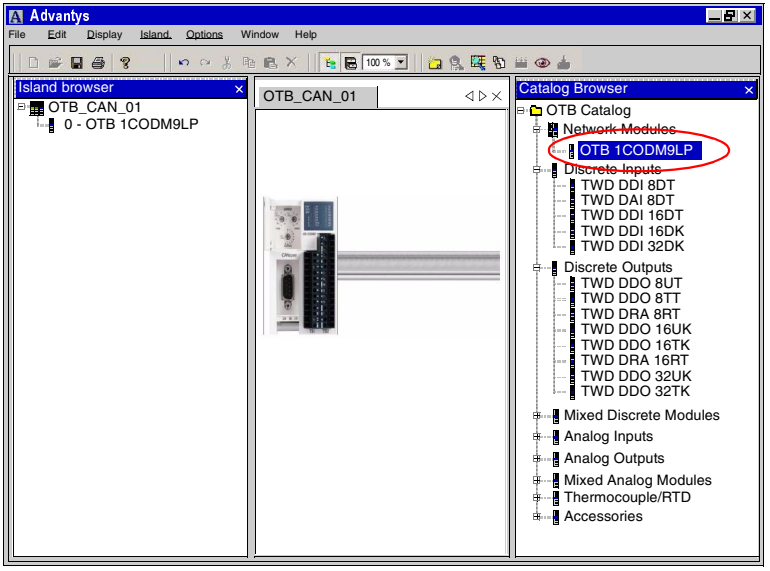
It is first necessary to install the Advantys Configuration Tool software that allows configuration of Advantys OTB and FTB I/O modules and splitters.

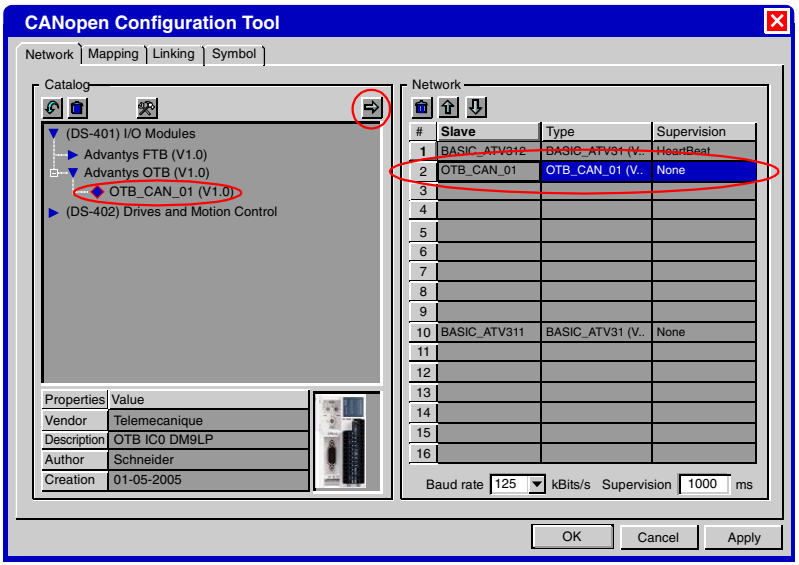
**Declare the Advantys OTB module**

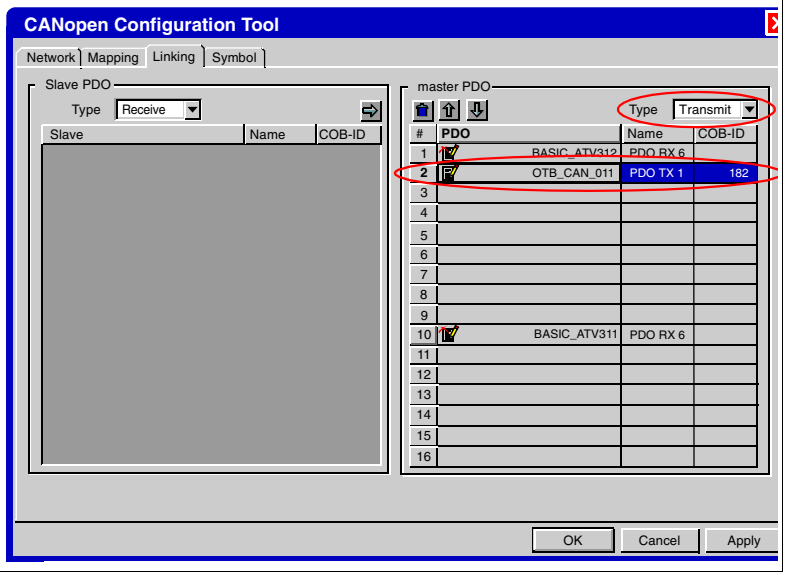
The following method allows declaration of the Advantys OTB I/O module in the Twido controller application.

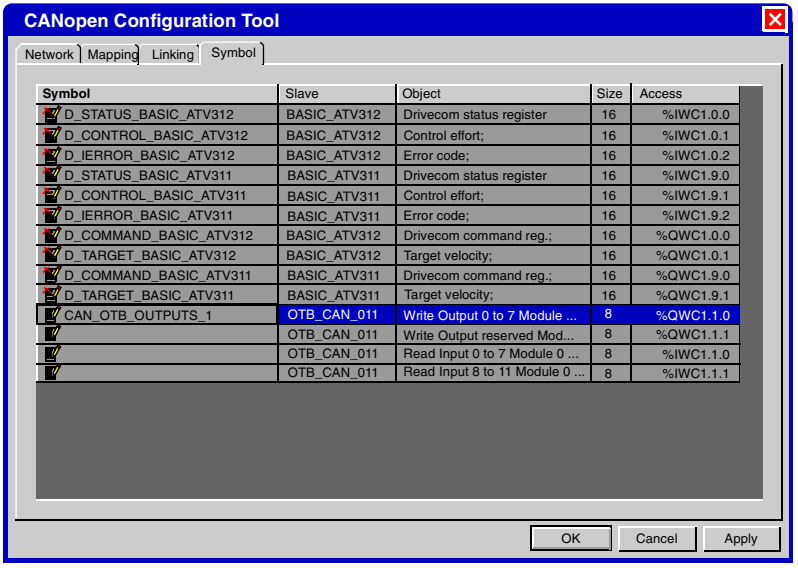
| Step | Action |
|---|---|
| 1 | Open the existing application using the TwidoSoft (TwidoSoft must be in disconnected mode).<br>Right click on the expansion bus and select "Configure".<br>  <br> |

| Step | Action |
|---|---|
| 2 | Expand the tree of the I/O Modules (DS-401) profile, select "Advantys OTB (V1.0)" and click on to launch configuration and addition of a new element:   |
| 3 | In the "New Island" window, enter "OTB_CAN_01" matching the name of the equipment that will be used in TwidoSoft. Next click on the "OK" button to confirm and launch the Advantys Configuration Tool application:   |

| Step | Action |
|---|---|
| 4 | Double click on the module "OTB1C0DM9LP" to add it in the new island.<br>  <br> |
| 5 | Perform a "File / Save".<br>Perform a "File / Quit".<br>The new island containing the Advantys OTB I/O module is then added to the catalog under the name "OTB_CAN_01". |

| Step | Action |
|---|---|
| 6 | Select "OTB_CAN_01 (V1.0)" in the "Catalog" area and click on to add the Advantys OTB in the Network area.<br>  <br><br>Note: The Advantys OTB is configured by default to the first free network address, that is the network address 2 in our example. |

| Step | Action |
|---|---|
| 7 | Select the "Linking" tab.<br>Use to assign the new Advantys OTB I/O module to the PDO no. 2, in both "Receive" and "Send":<br>  <br> |

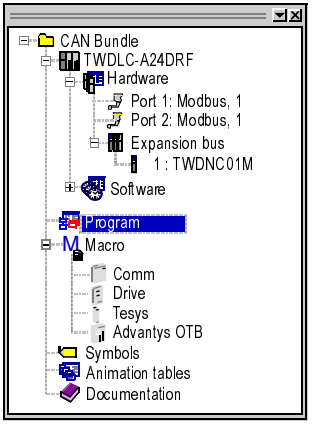
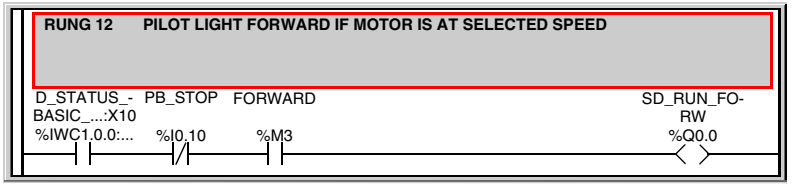
| Step | Action |
|---|---|
| 8 | Select the "Symbol" tab.<br>Enter, if necessary a "symbol" for the objects associated with the Advantys OTB I/O module:<br>● Double click in the object's "Symbol" field,<br>● Type the name of the "Symbol",<br>● Confirm using the "ENTER" key of the keyboard.<br>  <br> |
| 9 | Next click on the "OK" button to confirm the changes. The Advantys OTB I/O module is then declared in the Twido controller application. |

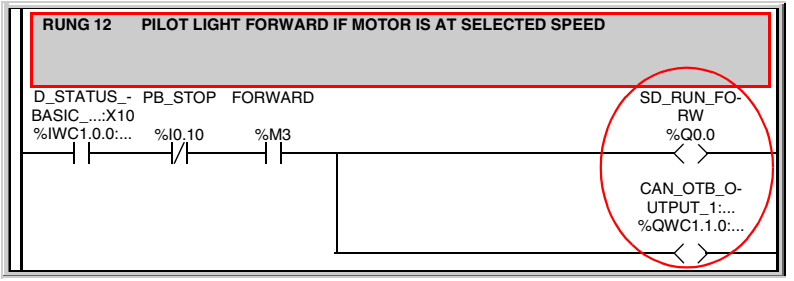
| Symbol | Slave | Object | Size | Access |
|---|---|---|---|---|
| D_STATUS_BASIC_ATV312 | BASIC_ATV312 | Drivecom status register | 16 | %IWC1.0.0 |
| D_CONTROL_BASIC_ATV312 | BASIC_ATV312 | Control effort; | 16 | %IWC1.0.1 |
| D_IERROR_BASIC_ATV312 | BASIC_ATV312 | Error code; | 16 | %IWC1.0.2 |
| D_STATUS_BASIC_ATV311 | BASIC_ATV311 | Drivecom status register | 16 | %IWC1.9.0 |
| D_CONTROL_BASIC_ATV311 | BASIC_ATV311 | Control effort; | 16 | %IWC1.9.1 |
| D_IERROR_BASIC_ATV311 | BASIC_ATV311 | Error code; | 16 | %IWC1.9.2 |
| D_COMMAND_BASIC_ATV312 | BASIC_ATV312 | Drivecom command reg.; | 16 | %QWC1.0.0 |
| D_TARGET_BASIC_ATV312 | BASIC_ATV312 | Target velocity; | 16 | %QWC1.0.1 |
| D_COMMAND_BASIC_ATV311 | BASIC_ATV311 | Drivecom command reg.; | 16 | %QWC1.9.0 |
| D_TARGET_BASIC_ATV311 | BASIC_ATV311 | Target velocity; | 16 | %QWC1.9.1 |
| CAN_OTB_OUTPUTS_1 | OTB_CAN_011 | Write Output 0 to 7 Module ... | 8 | %QWC1.1.0 |
| | OTB_CAN_011 | Write Output reserved Mod... | 8 | %QWC1.1.1 |
| | OTB_CAN_011 | Read Input 0 to 7 Module 0 ... | 8 | %IWC1.1.0 |
| | OTB_CAN_011 | Read Input 8 to 11 Module 0 ... | 8 | %IWC1.1.1 |

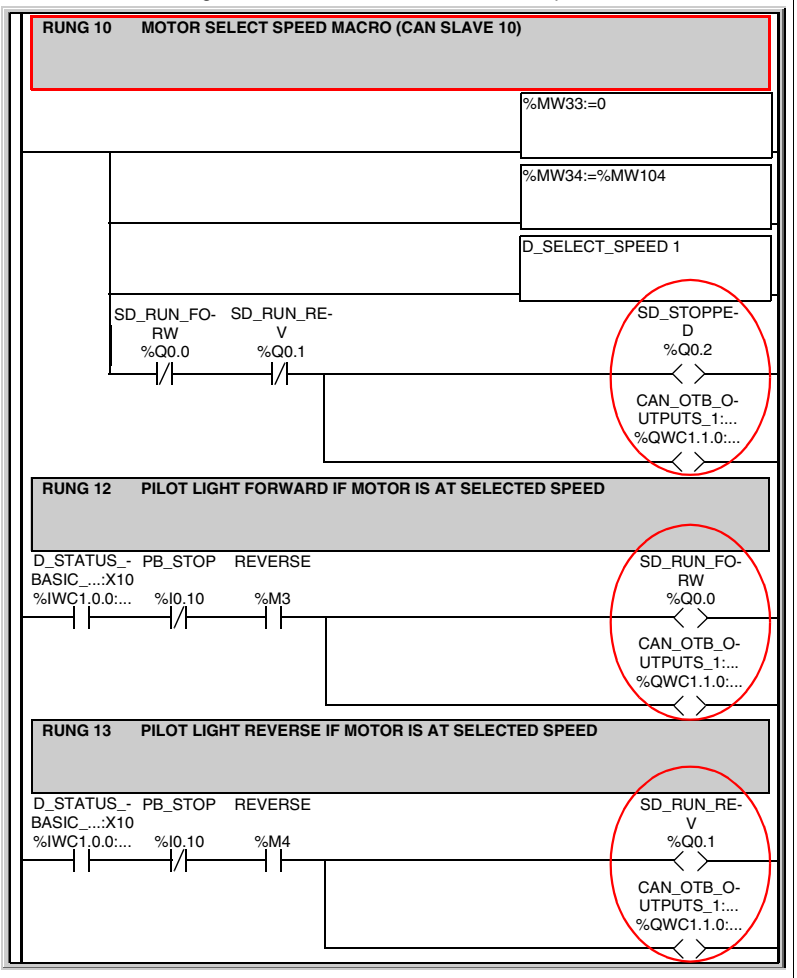
**Non-reversible**

The following method allows modification of the application to control outputs of the Advantys OTB I/O module the same as those of the Twido controller.

The following method consists in changing the lines that manage the outputs of the Twido controller by adding the outputs of the Advantys OTB.

| Step | Action |
|---|---|
| 1 | Double click on "Program" to open the programming window:   |
| 2 | Select a program line corresponding to the control of outputs of the Twido controller:   |
| 3 | Double-click on the electrical diagram to edit it. |

| Step | Action |
|---|---|
| 4 | Add, parallel to the output coil of the Twido controller (output %Q0.0), a coil to which the OTB output is applied: "%QWC1.1.0:X0".<br>Accept Changes<br>The control program line that simultaneously maintains the two outputs:<br>  <br> |

| Step | Action |
|---|---|
| 5 | Redo the same changes to be able to control the other outputs X1 and X2:   |
| 6 | Perform a "File / Save". |
| 7 | Load the new application into the Twido controller: Perform a "Controller/Connect" and click on the "PC -> Automate" button. |

# Add expansion modules to the Advantys OTB

# 9

## Principle

**Overview**

This section describes how to add I/O expansion modules to the Advantys OTB. These expansion modules allow to manage the Discrete and Analog I/O.

**What's in this Chapter?**

This chapter contains the following topics:


| Topic | Page |
|---|---|
| Mount expansion modules | 76 |
| Add expansion modules to the Advantys OTB in the Twido controller application. | 76 |

## Mount expansion modules

**Principle**

See reference guide no. 160384.

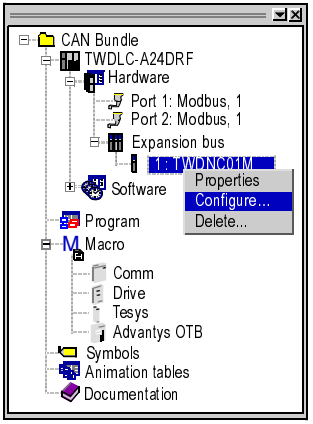
## Add expansion modules to the Advantys OTB in the Twido controller application.

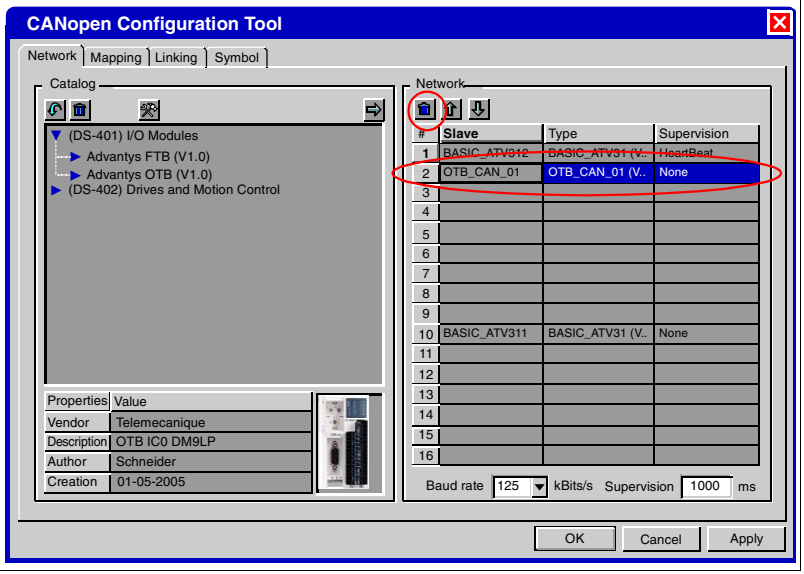
**Principle**

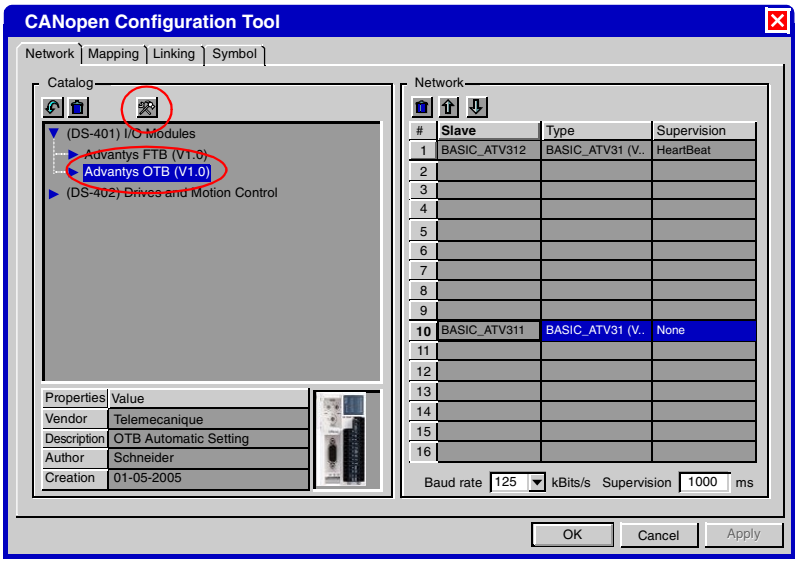
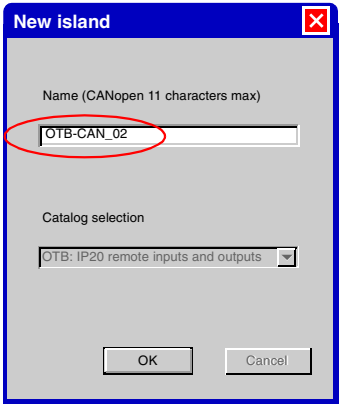
The objective is to modify the existing application in order to be able to manage the I/O of the Advantys OTB I/O module associated with two expansion modules.

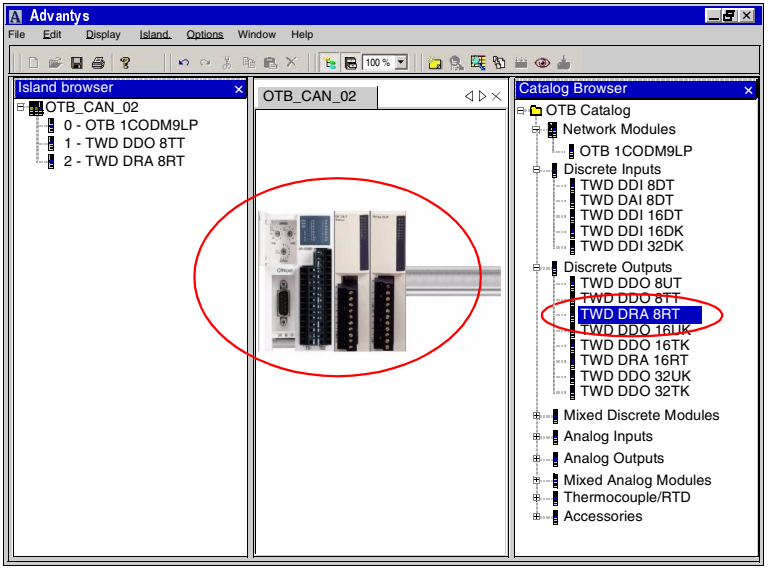
**Declare the Advantys OTB module**

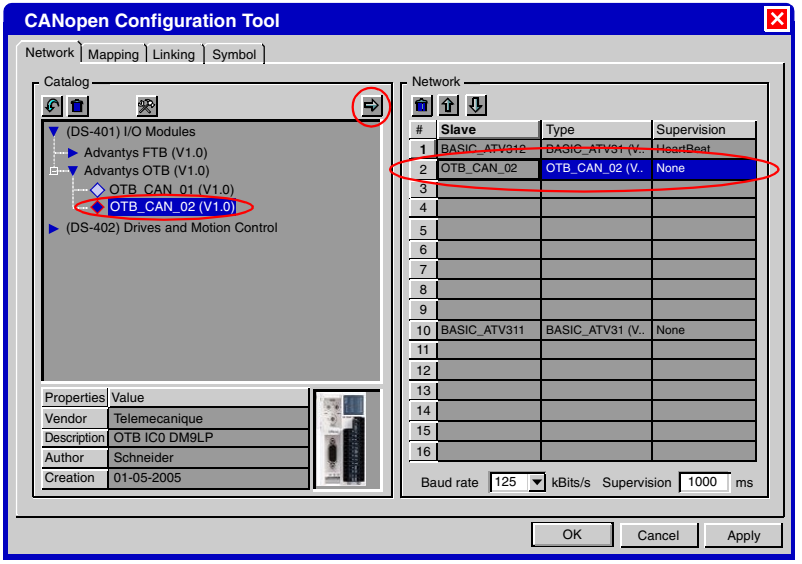
The following method allows declaration of the Advantys OTB I/O module in the Twido controller application.

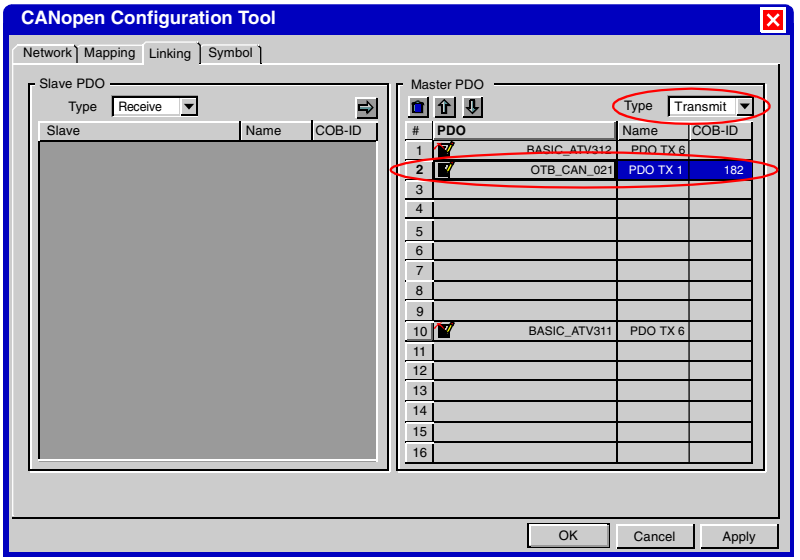
| Step | Action |
|---|---|
| 1 | Open the existing application using the TwidoSoft (TwidoSoft must be in disconnected mode).<br>Right click on the expansion bus and select "Configure".<br>  <br> |

| Step | Action |
|---|---|
| 2 | Select the module "OTB_CAN_01" in the "Network" area and click on to delete it:   |

| Step | Action |
|---|---|
| 3 | Expand the tree of the I/O Modules (DS-401) profile, select "Advantys OTB (V1.0)" and click on to launch configuration and addition of a new element:   |
| 4 | In the "New Island" window", enter "OTB_CAN_02" matching the name of the equipment that will be used in TwidoSoft. Next click on the "OK" button to confirm and launch the Advantys Configuration Tool application:   |

| Step | Action |
|---|---|
| 5 | Double click on the "OTB1C0DM9LP" I/O module to add it in the new island:<br>Do the same with the "TWDDDO8TT" and "TWDDRA8RT" expansion modules to add them to the new island:<br>  <br> |
| 6 | It is possible to double click on the image of each module to set the parameters (Mask, polarity, management of fallback modes, etc.).<br>Perform a "File / Save".<br>Perform a "File / Quit".<br>The new island containing the Advantys OTB I/O module and its expansion modules is then added to the CANopen catalog under the name "OTB_CAN_02". |

| Step | Action |
|---|---|
| 7 | Select "OTB_CAN_02 (V1.0)" in the "Catalog" area and click on to add the Advantys OTB in the "Network" area:<br>  <br><br>Note: The Advantys OTB is configured by default to the first free network address, i.e., the network address 2 in our example. |

| Step | Action |
|---|---|
| 8 | Select the "Linking" tab.<br>Use to assign the new Advantys OTB I/O module and its two expansion modules to the PDO no. 2, in both "Receive" and "Send" modes:<br>  <br> |
| 9 | Select the "Symbol" tab.<br>Enter, if necessary a "symbol" for the objects associated with the Advantys OTB I/O module:<br>● Double click in the object's "Symbol" field,<br>● Type the name of the "Symbol",<br>● Confirm using the "ENTER" key of the keyboard. |
| 10 | Click on the "OK" button to confirm. The Advantys OTB I/O module and its expansion modules are then declared in the Twido controller application. |

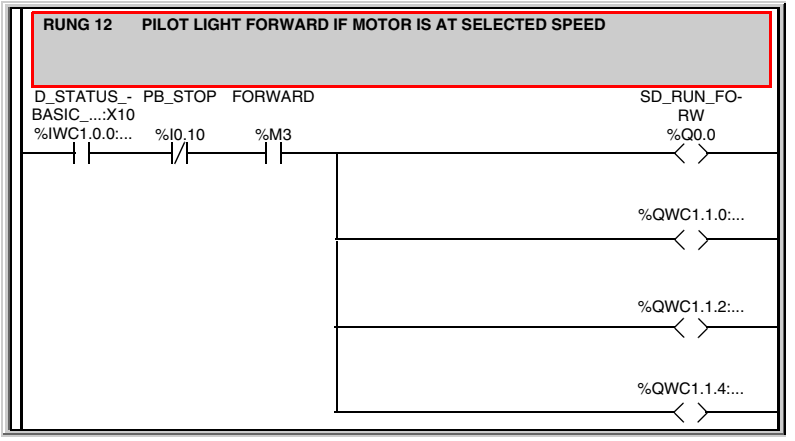
**Non-reversible**

The goal is to modify the application to manage the outputs of the Advantys OTB I/O module and of its expansion module the same as those of the Twido controller.

The method is identical to that described for the addition of an Advantys OTB by integrating the new outputs of the new island:

- %QWC1.1.0:X0 to X7 for the Advantys OTB "OTB1C0DEM9LP" module,
- %QWC1.1.2:X0 to X7 for the "TWDDO08TT" expansion module,
- %QWC1.1.4:X0 to X7 for the "TWDRA08RT" expansion module.

Here, for example, the line of the modified application managing the "FOWARD START" indicator LEDs:




Perform a "File / Save".

Load the new application into the Twido controller: Perform a "Controller/Connect" and click on the "PC -> Automate" button.

# Add an Advantys FTB I/O splitter

# V

## At a Glance

**Overview**

This section of the document presents a possible evolution of the main system, that is the addition of an Advantys FTB I/O splitter.

**Note:** If you are not using a speed controller or Advantys OTB I/O module in your application, erase the associated elements in the CANopen configuration as well as in the Twido controller application program.

**Application files**

Files for this configuration may be found in CD-ROM BUNDLE (DIA3CD3050101F) in the "Applicative files\Partie_V" folder for the Twido controller application.

**What's in this Part?**

This part contains the following chapters:


| Chapter | Chapter Name | Page |
|---|---|---|
| 10 | Hardware implementation of an Advantys FTB splitter | 85 |
| 11 | Software implementation of an Advantys FTB splitter | 89 |

# Hardware implementation of an Advantys FTB splitter

# 10

## At a Glance

**Overview**

This chapter describes hardware implementation of an Advantys FTB I/O splitter added to the main system.

**What's in this Chapter?**

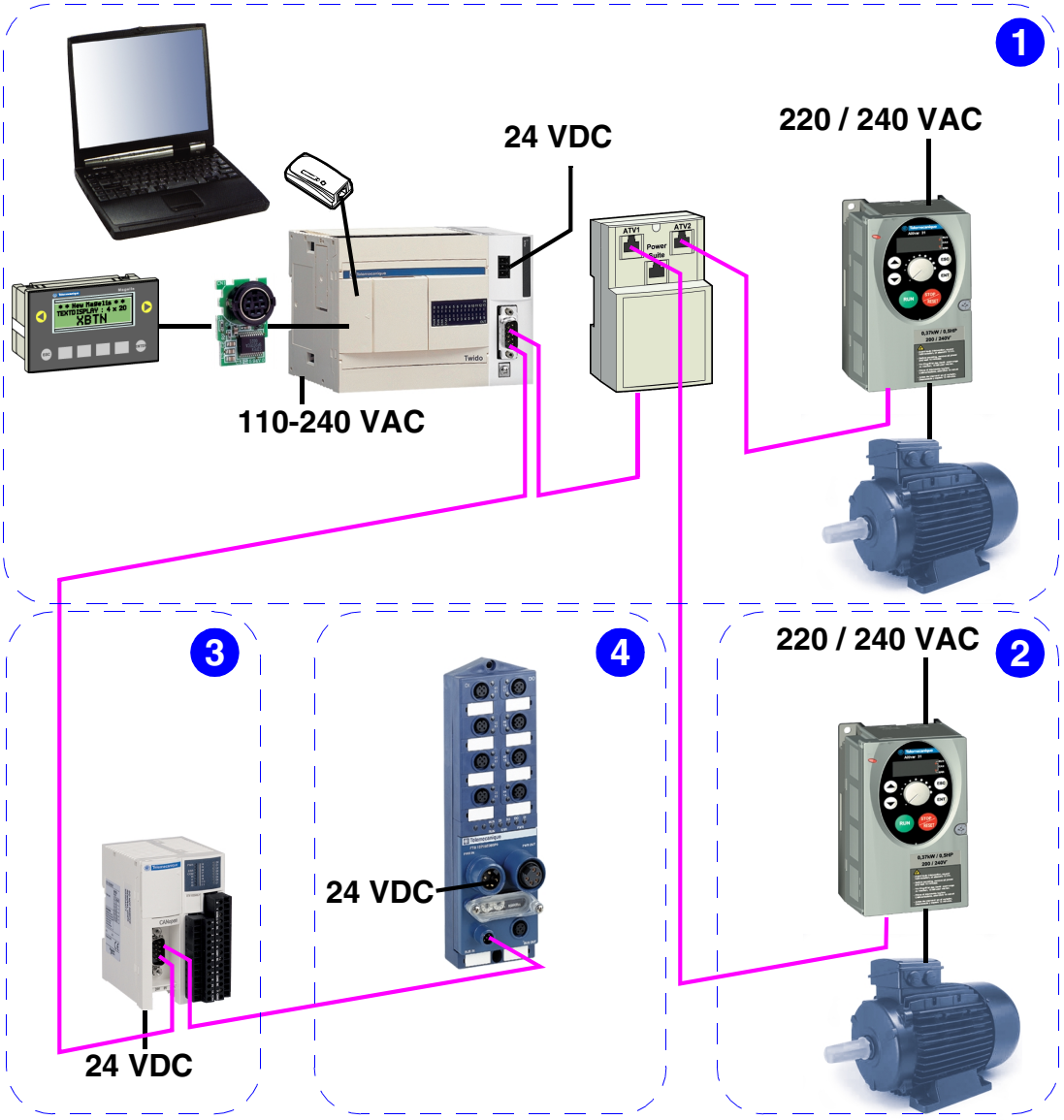
This chapter contains the following topics:


| Topic | Page |
|---|---|
| Cabling of the Advantys FTB I/O splitter | 86 |
| Cabling of the CANopen network | 87 |
| Power supply | 88 |

## Cabling of the Advantys FTB I/O splitter

**Installation diagram**

This part of the document covers the following mounting:



## Cabling of the CANopen network

**Principle**

The objective is to connect the Advantys FTB to the Advantys OTB using a cable.

**Select a cable**

To connect the Advantys FTB to the Advantys FTB, select one of the following cables:

| Reference | Cable length (m) |
|---|---|
| FTXCN3130 | 3 |
| FTXCN3150 | 5 |

**Advantys FTB side cabling**

The M12 end of the cable is connected to the Advantys FTB on the "BUS IN" base.

**Advantys OTB side cabling**

The "bare wire" end of cable is connected to the SUB-D 9 connector joined to the Advantys OTB (see *TAP-Twido Cable Preparation, p. 26*).

Cable pin assignment in the terminal of the SUB-D 9 connector:

| No. | Signal | Cable | Wire color |
|---|---|---|---|
| 6 | CAN_L | FTB/OTB | Blue |
| 7 | CAN_H | FTB/OTB | White |
| 8 | SHLD (CAN-GND) | FTB/OTB | (Bare cable shielding) |
| 9 | V+ | FTB/OTB | Red |
| 10 | GND | FTB/OTB | Black |

**Note:** Toggle the line end terminator of the SUB-D 9 connector on the Advantys OTB to "OFF".
Connect the FTXCNTL12 line end terminator to the "BUS OUT" base of the Advantys FTB.

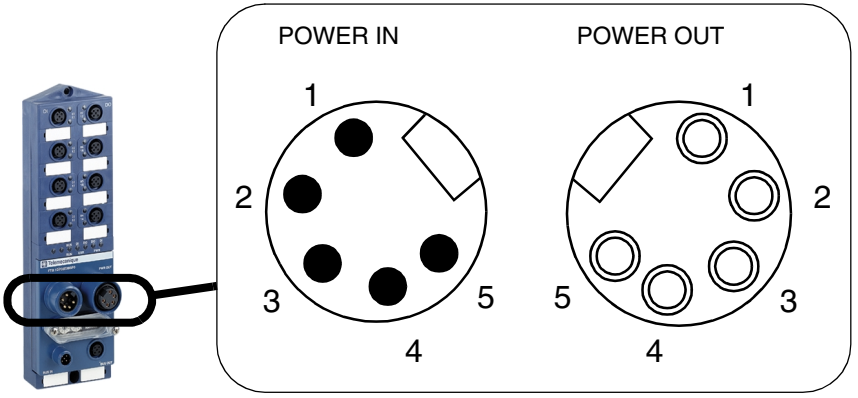
# Power supply

## Power on the Advantys FTB

Power on the Advantys FTB I/O splitter using one of the following cables:

| Reference | Cable length (m) |
|---|---|
| FTXDP2115 | 1,5 |
| FTXDP2130 | 3 |
| FTXDP2150 | 5 |

Wiring Diagram:




Pin Assignment:

| PIN No. | Description | Wire color | Printing on wire |
|---|---|---|---|
| 1 | 0 V | Black | 1 |
| 2 | 0 V | Black | 2 |
| 3 | PE | Green/Yellow | - |
| 4 | +24 V | Black | 3 |
| 5 | +24 V | Black | 4 |

# Software implementation of an Advantys FTB splitter

# 11

## At a Glance

**Overview**

This chapter describes software implementation of an Advantys FTB I/O splitter added to the main system.

**What's in this Chapter?**

This chapter contains the following topics:


| Topic | Page |
|---|---|
| Configuration of Advantys FTB communications | 90 |
| Add an Advantys FTB I/O splitter to the Twido controller application. | 91 |

## Configuration of Advantys FTB communications

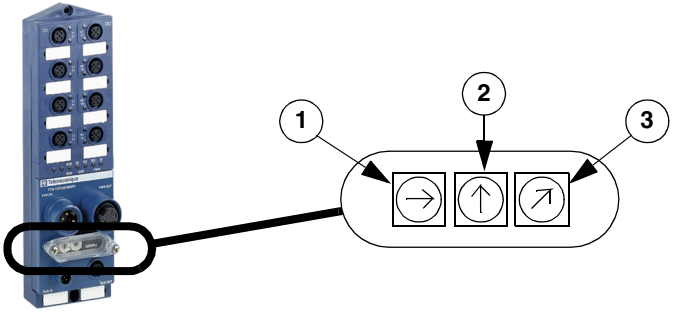
**Principle**

The system products must be configured according to the Twido application controller as follows:

- Address 1: ATV31
- Address 2: Advantys OTB
- Address 3: Advantys FTB
- Address 10: second ATV31
- Transmission Speed: 125 kBits/s

**Description**

Front panel of the Advantys FTB I/O splitter:




| No. | Function |
|---|---|
| 1 | Transmission speed encoder wheel |
| 2 | Network address (Node-ID x10) encoder wheel |
| 3 | Network address (Node-ID x1) encoder wheel |

**Method**

Configuration of Advantys FTB communication parameters:

| Step | Action |
|---|---|
| 1 | Cut off all power to the element. |
| 2 | Set encoder wheel 1 to the position corresponding to the required baud rate.<br>In the example: encoder wheel 1 is set to position 5 (125 kBits/s) |
| 3 | Set encoder wheels 2 and 3 to the position corresponding to the desired network address. In the example, the address is 3 (10x0 + 1x3):<br>● encoder wheel 2: position 0 (tens)<br>● encoder wheel 3: position 3 (units) |
| 4 | Reapply power to the Advantys FTB to implement the new configuration. |

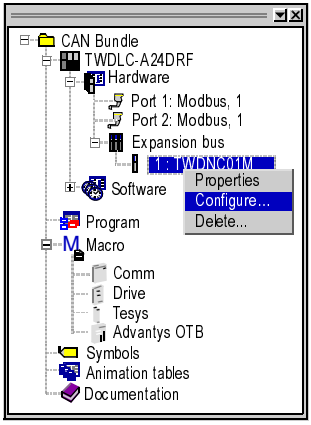
## Add an Advantys FTB I/O splitter to the Twido controller application.

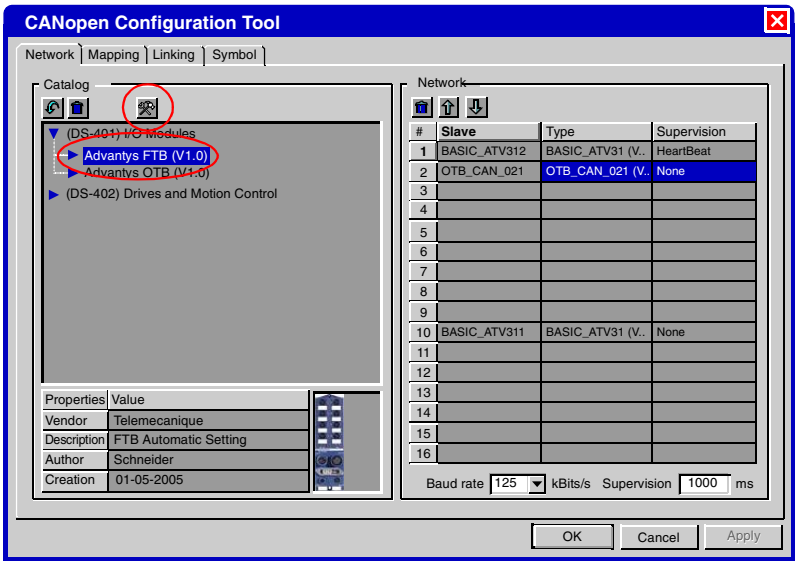
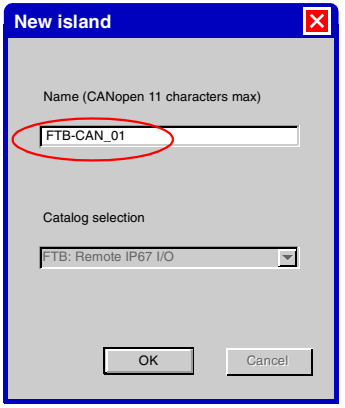
**Principle**

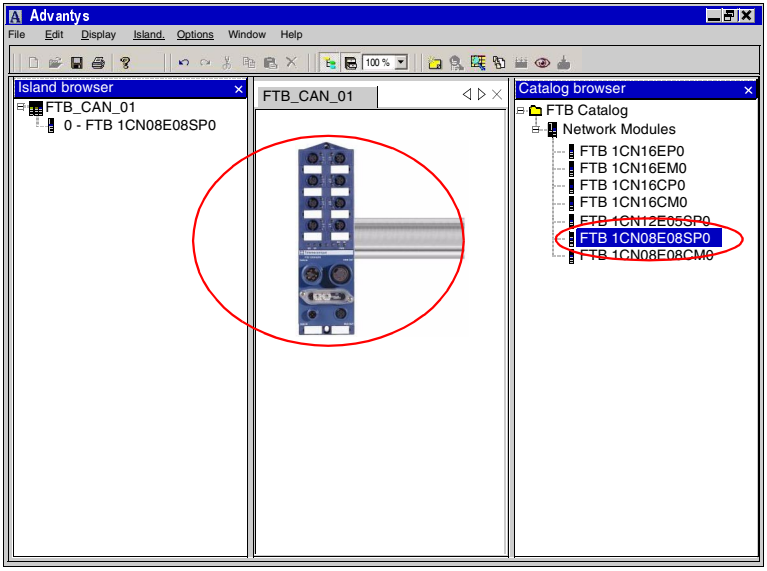
The objective is to modify the existing application in order to be able to manage the I/O of the Advantys FTB splitter.

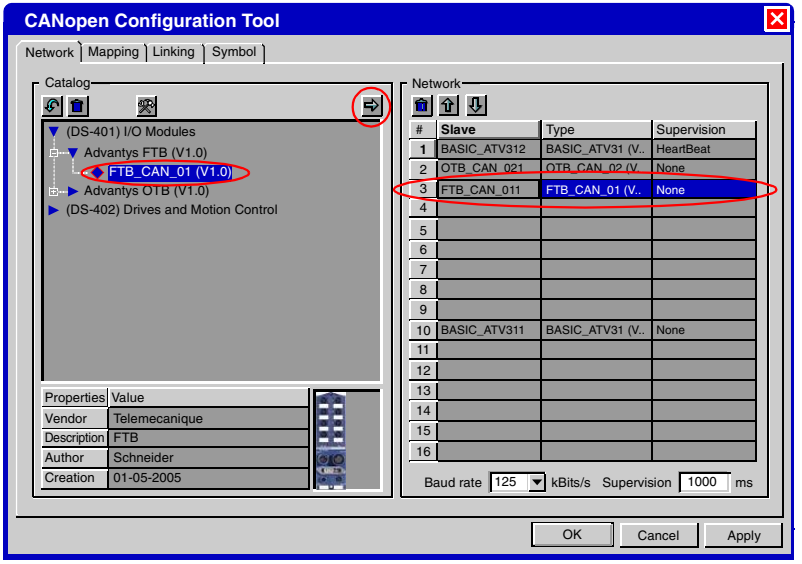
**Declare the Advantys FTB splitter**

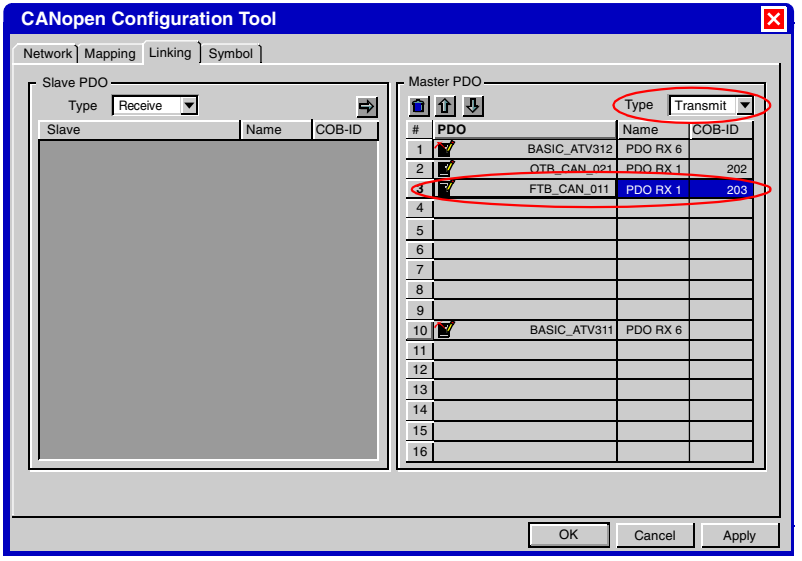
The following method allows declaration of the Advantys FTB I/O splitter in the Twido controller application.

| Step | Action |
|---|---|
| 1 | Open the existing application using the TwidoSoft software (TwidoSoft must be in disconnected mode).<br>Right click on the expansion bus and select "Configure".<br>  <br> |

| Step | Action |
|---|---|
| 2 | Expand the tree of the I/O Modules (DS-401) profile, select "Advantys FTB (V1.0)" and click on to launch configuration and addition of a new element:   |
| 3 | In the "New Island" window, enter "FTB_CAN_01" matching the name of the equipment that will be used in TwidoSoft. Next click on the "OK" button to confirm and launch the Advantys Configuration Tool application:   |

| Step | Action |
|---|---|
| 4 | Double click on the Advantys FTB I/O "FTB1CN08E08SP0" splitter to add it in the new island:<br>  <br> |
| 5 | It is possible to double click on the image of the splitter to set the parameters (Function, Mask, polarity, management of fallback modes, etc.).<br>Perform a "File / Save".<br>Perform a "File / Quit".<br>The new island containing the Advantys FTB I/O splitter is then added to the CANopen catalog under the name "FTB_CAN_01". |

| Step | Action |
|---|---|
| 6 | Select "FTB_CAN_01 (V1.0)" in the "Catalog" area and click on to add the Advantys FTB splitter in the "Network" area.<br>  <br><br>Note: The Advantys FTB is configured by default to the first free network address, i.e., the network address 3 in our example. |

| Step | Action |
|---|---|
| 7 | Select the "Linking" tab.<br>Use to assign the new Advantys FTB splitter to the PDO no. 3, in both "Receive" and "Send":<br>  <br> |
| 8 | Select the "Symbol" tab.<br>Enter, if necessary, a "symbol" for the objects associated with the Advantys FTB I/O splitter:<br>● Double click in the object's "Symbol" field,<br>● Type the name of the "Symbol",<br>● Confirm using the "ENTER" key of the keyboard. |
| 9 | Click on the "OK" button to confirm. The Advantys FTB I/O splitter is then declared in the Twido controller application. |

**Non-reversible**

The goal is to change the application to control the I/O of the Advantys FTB splitter the same as those of the Twido controller.

The method is identical to the one described for adding an Advantys OTB by integrating to the application the new I/O of the Advantys FTB splitter:

- %IWC1.2.0:X0 to X7 for inputs,
- %QWC1.2.0:X0 to X7 for the outputs.

Perform a "File / Save".

Load the new application into the Twido controller: Perform a "Controller/Connect" and click on the "PC -> Automate" button.

# Appendices

## At a Glance

**List of symbols**

The following pages contain the list of symbols used in the application described in part V of this document.

**What's in this Appendix?**

The appendix contains the following chapters:


| Chapter | Chapter Name | Page |
|---|---|---|
| A | List of symbols used in the application | 99 |

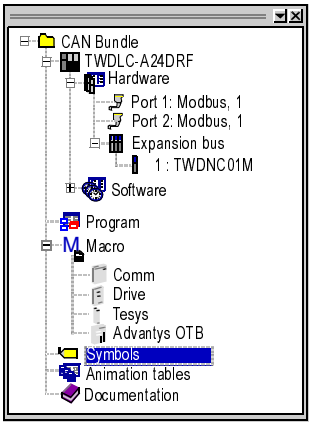
# List of symbols used in the application

# A

## List of symbols used in the application

**List of symbols**

In the Twidosoft software, double click on "Symbols" to display the list of symbols used in the application.



Here, for example, is the list of symbols used in the application described in part V of this document:

| Symbol | Number | Comment |
|---|---|---|
| PB_START_FORWARD | %I0.8 | |
| PB_START_REVERSE | %I0.9 | |
| PB_STOP | %I0.10 | |
| PB_SLOW_FAST | %I0.11 | |
| D_STATUS_BASIC_ATV312 | %IWC1.0.0 | |
| D_CONTROL_BASIC_ATV312 | %IWC1.0.1 | |
| D_IERROR_BASIC_ATV312 | %IWC1.0.2 | |
| OTB_CAN_INPUTS_1 | %IWC1.1.0 | |
| OTB_CAN_INPUTS_2 | %IWC1.1.1 | |
| FTB_CAN_INPUTS_1 | %IWC1.2.0 | |
| D_STATUS_BASIC_ATV313 | %IWC1.9.0 | |
| D_CONTROL_BASIC_ATV313 | %IWC1.9.1 | |
| D_IERROR_BASIC_ATV313 | %IWC1.9.2 | |
| FORWARD | %M3 | |
| REVERSE | %M4 | |
| PB_12_RF | %M12 | |
| XBT_INIT_CAN_EDGE | %M20 | test if the XBT function key was pressed to INIT CAN |
| XBT_OPER_CAN_EDGE | %M21 | test if the XBT function key was pressed to INIT CAN |
| D_STATE_0 | %MW0 | Altivar state |
| D_CANSTATE_0 | %MW1 | Altivar CANOpen state |
| D_ERROR_0 | %MW2 | Altivar error code |
| D_SETPOINT_MODE_0 | %MW3 | Altivar set-point mode |
| D_SETPOINT_0 | %MW4 | Altivar set-point |
| D_STATE_1 | %MW31 | Altivar state |
| D_CANSTATE_1 | %MW32 | Altivar CANOpen state |
| D_ERROR_1 | %MW33 | Altivar error code |
| D_SETPOINT_MODE_1 | %MW34 | Altivar set-point mode |
| D_SETPOINT_1 | %MW35 | Altivar set-point |
| CAN_COM_PARAM_1 | %MW80 | Communication parameters used to go back in operational mode after a slave pb |
| CAN_COM_PARAM_2 | %MW81 | |
| SD_SPEED | %MW104 | Speed entered with the XBT or selected by OTB input %IWC1.1.1:X3 |

| Symbol | Number | Comment |
|---|---|---|
| XBT_FTB_OUTPUTS | %MW105 | used to display information on the XBT |
| XBT_FTB_INPUTS | %MW106 | used to display information on the XBT |
| XBT_OTB_OUTPUTS | ESPAÑOL | used to display information on the XBT |
| XBT_OTB_INPUTS | %MW108 | used to display information on the XBT |
| XBT_DIALOG_TABLE_ALARM | %MW110 | Used to manage Alarm display on the XBTN400 |
| CAN_OPEN_SLAVE_STATUS_2_1 | %MW200 | |
| CAN_OPEN_SLAVE_STATUS_4_3 | %MW201 | |
| CAN_OPEN_SLAVE_STATUS_1 | %MW202 | |
| CAN_OPEN_SLAVE_STATUS_2 | %MW203 | |
| CAN_OPEN_SLAVE_STATUS_3 | %MW204 | |
| SD_RUN_FORW | %Q0.0 | |
| SD_RUN_REV | %Q0.1 | |
| SD_STOPPED | %Q0.2 | |
| D_COMMAND_BASIC_ATV312 | %QWC1.0.0 | |
| D_TARGET_BASIC_ATV312 | %QWC1.0.1 | |
| OTB_CAN_OUTPUTS_1 | %QWC1.1.0 | |
| OTB_CAN_OUTPUTS_2 | %QWC1.1.1 | |
| OTB_CAN_OUTPUTS_3 | %QWC1.1.2 | |
| OTB_CAN_OUTPUTS_4 | %QWC1.1.3 | |
| OTB_CAN_OUTPUTS_5 | %QWC1.1.4 | |
| OTB_CAN_OUTPUTS_6 | %QWC1.1.5 | |
| FTB_CAN_OUTPUTS_1 | %QWC1.2.0 | |
| D_COMMAND_BASIC_ATV313 | %QWC1.9.0 | |
| D_TARGET_BASIC_ATV313 | %QWC1.9.1 | |