

# On the Equivalence Between Type I Liouville Dynamical Systems in the Plane and the Sphere



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**Abstract** Separable Hamiltonian systems either in sphero-conical coordinates on an  $S^2$  sphere or in elliptic coordinates on a  $\mathbb{R}^2$  plane are described in a unified way. A back and forth route connecting these Liouville Type I separable systems is unveiled. It is shown how the gnomonic projection and its inverse map allow us to pass from a Liouville Type I separable system with a spherical configuration space to its Liouville Type I partners where the configuration space is a plane and back. Several selected spherical separable systems and their planar cousins are discussed in a classical context.

**Keywords** Separation of variables · Sphero-conical coordinates · Elliptic coordinates · Liouville dynamical systems · Trajectory isomorphism

## 1 Introduction

Hamiltonian systems in  $\mathbb{R}^2$  that admit separation of variables were completely determined by Liouville [1] and Morera [2], and can be classified, see [3], in four different types according to the system of coordinates where the separability is manifested: elliptic, polar, parabolic, and Cartesian, respectively. Thus Type I Liouville systems in  $\mathbb{R}^2$  are defined by natural Hamiltonians:  $H = K + \mathcal{U}$ ,  $K = \frac{m}{2} \left( \left( \frac{dx_1}{dt} \right)^2 + \left( \frac{dx_2}{dt} \right)^2 \right)$ , that are separable in elliptic coordinates [3].

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359

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