A generic heuristic for multi-project scheduling problems

with global and local resource constraints (RCMPSP)

Abstract. This paper presents a novel algorithm to solve the multi-project scheduling problem with resource constraints (RCMPSP). The algorithm was tested with all the problems proposed in the Multi-Project Scheduling Problem Library (MPSPLib), which is the main reference to benchmark RCMPSP algorithms. Our analysis of the results demonstrates that this algorithm, in spite of its simplicity, outperforms other algorithms published in the library in 16% of the cases and holds the best result in 27% of the cases. These results, along with the fact that this is a general-purpose algorithm, makes it a good choice to deal with limited time and resources in Portfolio Management.

Keywords. Project Management, Project Scheduling, Portfolio Management, Multi-project Scheduling, RCMPSP, MPSPLib.

1 Introduction

Project Scheduling involves finding a start and finish time for all the project activities, considering a set of limitations such as precedence relations, temporary restrictions and resource constraints, while a predefined scheduling objective is optimized.

The real impulse for Project Scheduling took place with the emergence of scheduling methods based on Graph Theory in the late 1950s, such as PERT (Program Evaluation and Review Technique) (Malcolm et al. 1959), CPM (Critical Path Method) (Kelley and Walker 1959) or ROY (Algan et al. 1962). All of these methods allowed calculating the project duration and the start and finish times of the activities in a mechanical and relatively easy way.

However, these methods assumed that all the resources required by the activities would be available at the time of their execution. This assumption is unrealistic in practice because resources are normally shared between several activities in the project. Whenever two or more activities need the same resource at the same time, it needs to be determined what activities get the resource (and can be executed at the scheduled moment), and what activities need to be re-scheduled (i.e. be delayed, be interrupted or be executed more slowly). This decision has to be made repeatedly during all the scheduling process. Consequently, these constraints often lead to a complex scheduling problem that does not guarantee finding the optimal schedule for a project. (Villafañez et al. 2014a).

Later in time, several linear techniques started to be applied in order to try to solve this scheduling problem (Patterson 1973, 1984; Demeulemeester and Herroelen 2002). Over the years, this problem began to be called Resource-Constrained Project Scheduling Problem (RCPSP) and it became a field of research in the Project Management's literature (Hartmann and Briskorn 2010).

However, if we focus on real-life scheduling situations, companies do not normally handle a single project but a set of projects (Villafañez et al. 2014b). This multi-project case obviously increases the difficulty of the scheduling process due to the possible existence of resources that need to be shared between several projects (e.g. facilities, machines, human resources, etc.). The study of this issue was given the name RCMPSP (Resource-Constrained Multi-Project Scheduling Problem) (Fendley 1968; Davis 1969).

In this paper, we present the algorithm P-SGS/MIN-SLK¹ for the resolution of the RCMPSP (multiproject case). It is an adaptation of a method proposed by Kolisch (1996a; 1996b) that was used to solve the RCPSP (mono-project case) (Kolisch and Hartmann 1999; Hartmann and Kolisch 2000). We also present the results obtained after its application to solve all of the scheduling problems collected in a well-known repository of RCMPSP problems: the library MPSPLib² (Homberger 2007). After testing the algorithm with all of the 140 problems proposed in MPSPLib, we found that it provides better results than many other solutions published in the library. This is in spite of the fact that P-SGS/MIN-SLK is a general-purpose algorithm whereas other algorithms whose solutions were published in the library were built ad-hoc (i.e. they were specifically adapted to solve a particular scheduling problem). Our achieved solutions for these problems have been uploaded to the library and can be found under the name PSGSMINSLK³.

¹ Parallel Schedule Generation Scheme (P-SGS) and minimum activity total slack (MIN-SLK) as a priority rule

² www.mpsplib.com

³ <u>http://www.mpsplib.com/ranking.php?method=&criterion=tms&j=&p=&g=</u>

The rest of the manuscript is organized as follows: in Section 2 we briefly review some techniques for Project Scheduling in order to provide a framework for the algorithm that we present in this paper. Section 3 describes the heuristic P-SGS/MIN-SLK that we have implemented. Then, in Section 4 we present an example of the application of this algorithm in a simplified multi-project case. In section 5, we show the results of the application of the algorithm to all of the instances proposed in the library MPSPLib and we prove that, in spite of its simplicity, it outperforms many other algorithms designed to solve particular problems ad-hoc. Finally, in section 6, we present the conclusions of this work and discuss about some questions for future research.

2 Background on Project Scheduling: some approaches to solve RCPSP (mono-project) and RCMPSP (multiproject)

A feasible scheduling requires finding a proper combination of resources for the activities within the project (mono-project case, RCPSP) or within the projects (multi-project case, RCMPSP) in such a way that certain resource capacities and time constraints are met.

Nevertheless, finding the optimal solution by means of the classical methods proposed by Operational Research is not feasible even with the most recent computer systems. In fact, both RCPSP and RCMPSP are considered in terms of Complexity Theory as NP-Hard problems in strong sense (Blazewicz et al. 1983). This means that, whenever a feasible solution is found, it is not possible to know if this solution is optimal in the case of complex problems (Bartusch et al. 1988; Schirmer 1996).

Both RCPSP and RCMPSP can be conceptually modelled as a linear problem (Pritsker et al. 1969; Alvarez-Valdés Olaguíbel and Tamarit Goerlich 1993; Kaplan 1996; Mingozzi et al. 1998; Klein 2000). However, due to the difficulties in finding the optimal solution for the RCMPSP with this formulation, the scientific community has recently explored alternative ways of tackling this issue. These methodologies include heuristics and metaheuristics, such as ant colony optimization algorithms (Fink and Homberger 2013), simulated annealing (Dalfard and Ranjbar 2012), combinatorial auctions (Araúzo Araúzo et al. 2010; Villafáñez and Poza 2010; Song et al. 2016), genetic algorithms (Pérez et al. 2015) or multi-agent systems (Zheng et al. 2014). More recently, statistical learning techniques have proved to be promising in the field of Project Scheduling (Acebes et al. 2015; Wauters and Vanhoucke 2017), and also in other fields (Semwal et al. 2015, 2016, 2017).

These resolution methods are usually organized into two categories, namely **centralized approaches** (C-RCMPSP) and **decentralized approaches** (D-RCMPSP) (Villafañez et al. 2014b).

The centralized approach was introduced by Pritsker, Watters, et al. (1969) and Kurtulus & Davis (1982). According to this approach, a unique decision-maker decides the scheduling for all the projects (Blazewicz et al. 1983; Kolisch et al. 1995; Kolisch and Sprecher 1996; Kolisch 1996b; Brucker et al. 1999). Therefore, the centralized methods work well for the optimization of global objectives in the set of projects, such as the minimization of the total makespan (TMS) (Kurtulus and Davis 1982; Özdamar and Ulusoy 1995). In practice, the C-RCMPSP tackles the RCMPSP as an equivalent mega-project with a single critical path that can be solved as an RCPSP (see Figure 1).



Figure 1. Conceptual description of the centralized approach for the RCMPSP (C-RCMPSP)

The D-RCMPSP, however, considers several independent decision entities: one for each project and another for the portfolio (Confessore et al. 2002, 2007; Fink and Homberger 2015) (see Figure 2).

This approach does not only allow applying a global optimization criterion for the portfolio (as in the C-RCMPSP case), but it also allows each project to maintain certain control over its own critical path in the scheduling process, while trying to optimize its schedule based on different possible project performance measures.



Figure 2. Conceptual description of the decentralized approach for the RCMPSP (D-RCMPSP)

Focusing on the centralized methods, the priority rule-based approach for solving the mono-project case (Kelley 1963; Kolisch 1996b) is the most widely used technique to solve the multi-project case due to its simplicity (Herroelen 2005). This heuristic uses two components in order to build feasible project schedules that respect the resource constrains, namely: a Priority Rule (PR), which is the criterion (or criteria) used to determine the order in which the set of project activities whose predecessors have been completed (i.e. candidate activities) will be tried to be scheduled, and a Schedule Generation Scheme (SGS), which is the particular procedure used to obtain the list of candidate activities.

On the one hand, the most well-known generation schemes are (Boctor 1990):

- *Serial Schedule Generation Scheme (S-SGS):* an algorithm determines the order in which the activities will be tried to be scheduled <u>only once at the beginning of the scheduling process</u>.
- Parallel Schedule Generation Scheme (P-SGS): the algorithm dynamically re-determines the activities that can be scheduled at every scheduling period On the other hand, the priority

rule determines the order in which the activities whose predecessors have been completed will be tried to be scheduled. There exist a wide range of priority rules (Lova and Tormos 2001; Lova et al. 2006). They are usually based on one or more of these sources of information: activities information (e.g. their processing times or cost estimates), resources information (e.g. information about the resources constraints), network information (e.g. the number of immediate or total successors) scheduling information (e.g. the activities' earliest start time, latest finish time, free slack or total slack).

3 Implementation of the algorithm P-SGS/MIN-SLK

Following Rainer Kolisch (1996), our algorithm to solve the RCMPSP is a **centralized method**, which is based, as discussed in Section 2, on two components: a scheduling generation scheme and a priority rule. Concretely, the algorithm uses a **parallel schedule generation scheme** (P-SGS) and the **minimum total slack** (MIN-SLK) as a priority rule. The combination of these terms gives name to the heuristic that we have implemented to solve the RCMPSP: **P-SGS/MIN-SLK**.

Figure 3 shows a flow diagram of our implementation of the heuristic. The basic idea of the algorithm is the following: first, we create a preliminary schedule following the Critical Path Method (CPM): this implies that the resource constraints are ignored (i.e. the activities are scheduled as if the number of resources and their capacity were infinite). This leads to a tentative schedule that cannot be implemented because the resources required by the activities may not be available at the times they are requested. However, it will be the basis of the scheduling process.

Then, following the guidelines of a parallel scheduling generating scheme, at every time step we create a list with all the activities that can potentially be scheduled at the current time. This list contains activities from several projects whose predecessors have already been completed. We will call these activities 'candidate activities'.

The next step is to determine the order in which the candidate activities will be tried to be scheduled. The criterion used to sort this list (i.e. the priority rule) is the minimum total slack. This means that the candidate activities will be prioritized from the shortest to the longest total slack.



Figure 3. Flow diagram of the implementation of the P-SGS/MIN-SLK heuristic

Once we obtain the prioritized list of candidate activities, we try to schedule them one by one, starting from the first activity in the list (i.e. the one with the shortest total slack). In order to ensure the nonviolation of the resource constraints, we check if the resources needed by that activity are available during the entire duration of that activity (notice that we assume that the activities cannot be interrupted during its execution). Depending on the availability of resources, two things can happen: if there are enough resources available, then the activity is scheduled and the resources' availability for the next periods is updated (i.e. the previous resource's availability minus the amount of resource consumed by the activity that has just been scheduled during its whole execution). However, if the amount of resources is not enough, that activity will be delayed one time slot, when the resource constraints might meet. In any case, the activity is removed from the list of candidate activities.

Afterwards, we will proceed in the same way with the next candidate activity in the list and so forth. The current scheduling step finishes when the list of candidate activities is empty.

We will proceed likewise in the successive scheduling steps until all the activities have been scheduled. The tentative scheduled obtained at the beginning of each time step will contain two types of activities: activities that have already been scheduled in previous time steps (whose scheduling is definitive); and activities that are yet to be scheduled (which will be tentatively scheduled with the CPM method, and that are still subject to delays if the resources they need are not available).

As long as the priority rule is concerned, it is important to mention that ties are possible since two or more activities might have the same total slack. In order to break these ties, we use a secondary prioritization rule: random selection, which means that ties are broken randomly. The randomness introduced by this secondary priority rule provokes that different runs of the algorithm may yield different feasible solutions for the same problem. Consequently, we can apply the algorithm repeatedly and then retain the best solution for each iteration. As a result, the larger the number of executions of the algorithm, the higher the likelihood of finding the optimal solution.

4 Multi-project scheduling with P-SGS/MIN-SLK

For illustrative purposes, let us consider a simplified case with only three projects and two resources. For a better interpretation of the scheduling process, we will assume that these three projects form a project portfolio for a company. We will also consider that both resources are shared between all the three projects (i.e. global resources) for the sake of simplicity. However, P-SGS/MIN-SLK supports both local and global resources as stated before. The precedence relationships of the three projects are shown in (Figure 1, left). Recall that the heuristic P-SGS/MIN-SLK is a centralized method and thus it handles the set of projects as a virtual 'mega-project' composed of the activities of all its comprising projects (Figure 1, right).

• Initialization (t = 0)

The top of Figure 4 shows the schedule obtained with the Critical Path Method (CPM). Recall that in this tentative schedule, the resource consumption is ignored. Following this criterion, the Critical Path Duration (CPD) for projects 1, 2 and 3 are respectively 22, 21 and 18 time units. In order to illustrate the functioning of the algorithm, let us assume that the three projects start in different dates: project 1 will start in time-slot 0, whereas projects 2 and 3 will start in time-slots 1 and 5, respectively.

The duration of the whole portfolio (i.e. TMS, Total MakeSpan) is calculated as the difference between the finish date of the last activity of the portfolio and the start date of the first activity of the portfolio, which is 23 time units in this example, as Figure 4 shows.

The bottom of Figure 4 shows the number of resource units required at every time step for the implementation of this initial schedule. In this simplified example, we have two resources whose maximum capacity is 7 and 5 units per time-slot respectively. Notice that these two resources are shared by the three projects in the portfolio (i.e. they are 'global resources' according to the RCMPSP's nomenclature). The amount of resources (1 and 2) required is shown in brackets next to each activity. As shown in Figure 4, the CPM scheduling for this portfolio exceeds the maximum capacity of both resources at several time-slots: the maximum capacity of resource 1 is exceeded in time-steps 4 to 15 and the maximum capacity of resource 2 is exceeded in time-steps 5 to 8. This implies that this temporary schedule is not viable.

We create the list of candidate activities (i.e. activities that potentially can start at the current time-slot because either they have no predecessors or all of their predecessors have already been scheduled). In this case (Figure 4), there is only one candidate activity: *activity 1.2* (i.e. project 1,

activity 2). Since there is only one candidate activity, the prioritization algorithm obviously determines that this is the next activity to schedule.



Figure 1. Initial (CPM) scheduling and demand of resources at time-slot t = 0

Afterwards, the algorithm checks if all the resources needed by this activity are available during its whole duration (i.e. 3 units of resource 1 plus 3 units of resource 2, both during 4 time-slots). Since no activities have yet been scheduled, the current availability of resources equals the

resource's maximum capacity (7 units for resource 1 and 5 units for resource 2). Since all the resources are available during the whole duration of the activity, it is definitely scheduled between time-slots 1 and 4.

The current availability of resources is now updated by subtracting the amount of resources consumed by the activity that has just been scheduled from the amount of resources available before that activity was scheduled. In this case, the scheduling of the activity 1.2 modifies the availability of resources 1 and 2 during the next four time-steps, as Figure 5 shows. Since there are no more candidate activities, the first step of the scheduling process ends at this point. Should there be more candidate activities in the current step, the algorithm would try to schedule them following the order in the list of candidate activities, taking into account the changes in the availability of resources as the activities are scheduled.



Figure 5. Resource availability after time-step t = 1

• An intermediate time-step: t = 15

A temporary schedule is generated at the beginning every intermediary step. This temporary schedule is composed of two types of activities: on the one hand, the activities that could be scheduled in previous steps (whose schedule is final) and, on the other hand, a set of activities that are yet to be scheduled, which will be temporarily scheduled according to the CPM and are subject to be delayed during the rest of the scheduling process.

At this point, the activities 1.2, 1.3, 1.4 (project 1), 2.2, 2.3 (project 2), 3.2, 3.3 (project 3) have already been scheduled in previous time-steps. These activities are shown dashed in the top of Figure 6. Notice that the algorithm guarantees that the activities that have been scheduled so far

do not violate the maximum capacity of any of the resources. The scheduling for these activities is definitive.



Figure 6. Scheduling process at time-step t = 15

The rest of the activities (1.5, 1.6, 2.4, 2.5, 2.6, 3.4, 3.5 and 3.6), which have not been scheduled in previous time-steps, are tentatively scheduled according to the CPM (see Figure 6), which

means that its schedule is subject to change in the current or in later time steps. If we compare this tentative schedule with the one created in time-step 0 (Figure 5), it is to remark that the activities 2.4 and 2.5 could not be scheduled to start at t=8 as it was initially planned because at that time the resources needed by these activities were allocated to other activities (see bottom of Figure 6). Consequently, during time-steps 8 to 16 these two activities were delayed, once at a time-step.

There are five candidate activities at the current time-step as Figure 6 shows: 1.5, 2.4, 2.5, 3.4 and 3.5. The priority rule prioritizes the candidate activities from the shortest to the longest total slack, which determines the order in which these activities will be tried to be scheduled: 3.4, 2.5, 1.5 2.4 and 3.5. Notice that the activities 3.4, 2.5 and 1.5 have the same total slack, but this tie is solved randomly. Following this order, the activity 3.4 is successfully scheduled.

The bottom of Figure 6 shows the use of resources during the scheduling process. After subtracting the resources consumed by that activity, there are still enough resources to schedule the activity 2.5, which is successfully scheduled. However, the activity 1.5 cannot be scheduled at this time-step because there are not enough resources remaining (there is only one unit of resource 1 available during time-steps 15 to 22 whereas this activity requires four units of this resource). A similar situation occurs with activity 2.4, which cannot be scheduled due to lack of resources. The activity 3.5, however, is successfully scheduled since the four units of resource 2 it requires are available during its whole duration.

Notice that the candidate activities that could not be scheduled in the current iteration will be delayed one time-slot in the next iteration provisional scheduling (and so will all of their successors).

• Final schedule: time-step t = 30

After a number of steps, the algorithm provides a feasible schedule in which all the resource constraints are met (Figure 7). At this point, the dummy activities 2.7 and 3.7 are scheduled. Since there are no more pending activities, the scheduling process ends at this point, yielding a total make-span (i.e. duration of the whole portfolio) of 30 time units.

Notice that the activities 1.5 and 2.4, which could not be scheduled in time-step 16, become candidate activities during time-steps 17 to 22, but they could not be scheduled due to lack of resources. Consequently, they were successively delayed one time-unit. This situation persisted until time-step 22 and time step 23, in which the activities 1.5 and 2.4 were scheduled, respectively.



Figure 7. Final schedule at time-step t = 30

5 MPSPLib as a benchmark for P-SGS/MIN-SLK

In order to test the performance of the heuristic P-SGS/MIN-SLK, we made full use of MPSPLib, which is currently the most accepted collection of multi-project problems to test, evaluate, and compare different RCMPSP algorithms proposed by the scientific community (Wauters et al. 2015). MPSPLib⁴ (Multi-Project Scheduling Problem Library) is a well-known public library that contains a collection of 140 artificial multi-project problems. It was initially proposed by Jörg Homberger in order to test a decentralized RCMPSP based on a multi-agent system (Homberger 2007). Each of these 140 multi-project problems is a combination of several mono-project problems that had been previously collected in the library PSPLib⁵ (Library for Project Scheduling Problems) by Rainer Kolisch & Sprecher (1996). Although MPSPLib was initially conceived to test the decentralized multi-project problem, DRCMPSP, it is thoroughly valid for the centralized problem, CRCMPSP (Wauters et al. 2015).

Each problem is a combination of several projects with similar features in terms of number of activities. However, they are very different when it comes to the intensity of use of the resources shared by the activities. The library considers two types of resources: local resources (they can be used exclusively by the activities of one of the projects) and global resources (they can be shared between activities of different projects). MPSPLIB is, to our knowledge, the only public library that considers the complexity introduced by the consideration of both local and global resources in the same problem. Although the number of global resources varies from one problem to another, there is always at least one global resource (notice that if all the resources were local, that would not be considered as a RCMPSP, but simply a combination of several RCPSP). Either global or local, all the resources are considered renewable, i.e. the total capacity of each resource has a constant value per time slot during the whole time horizon.

This library does not only propose a collection of multi-project problems to test RCMPSP heuristics but it also offers researchers the possibility of uploading the results obtained with their algorithms. It

⁴ <u>http://www.mpsplib.com</u>

⁵ http://www.om-db.wi.tum.de/psplib/library.html

should be taken into account, however, that testing an algorithm with a library of instances is just one part of the process of evaluation (Barr et al. 1995) since it also depends on the hardware equipment and the quality of the code used for its implementation. Always bearing this in mind, MPSPLib considers three measures as an indicator of the quality of the scheduling obtained with an algorithm:

- *Total Makespan (TMS):* it is the duration of the whole set of projects, measured as the time elapsed between the beginning date of the first activity and the ending date of the last activity in the set of projects.
- *Average Project Delay (APD):* For a single project, the project delay (PD) is the difference between the critical path duration of the project (which ignores the resources constraints) and the duration of the final schedule (which meets these constraints). For a set of projects, the APD is the arithmetic mean of the PD of the projects comprising it.
- *Standard Deviation of Project Delay (DPD):* Similar to APD, but considering the standard deviation instead of the arithmetic mean.

The problems collected in MPSPLib are artificial. However, from a more realistic point of view, the set of projects comprising each RCMPSP could be considered as the portfolio of projects run by a company. In this case, it is reasonable to consider that, among these three indicators, the most useful for a generic company would be the total makespan (TMS). A company would probably wish to minimize the execution time of its whole portfolio (TMS) rather than trying to obtain a similar delay in all the projects comprising the portfolio (APD or DPD). This reason led us to use the total makespan as an indicator of the performance of P-SGS/MIN-SLK.

After applying the heuristic P-SGS/MIN-SLK to solve all of the 140 datasets, we uploaded the results into MPSPLib (a summary of this information can be found in the Appendix to this article⁶). Each row in the table compares the resulting total duration of the set of projects (total makespan, TMS) provided by our implementation (under the name of PSGSMINSLK) and the best solution achieved

⁶ The results can be found under the name of PSGSMINSLK at MPSPLib: <u>http://www.mpsplib.com/ranking.php?method=&criterion=tms&j=&p=&g=</u>

by other algorithms. We observe that the results provided by P-SGS/MIN-SLK are at least as good as other solutions in 38 / 140 problems, that is to say, over 27% of the datasets.

As seen before, P-SGS/MIN-SLK is based on a priority rule. It should be taken into account that the performance of a particular priority rule depends on the concrete problem where it is applied and vice versa, the same algorithm with a different priority rule may lead to very different results when applied to the same problem. It is not possible to know what priority rule will perform best a priori (Vázquez et al. 2013). However, P-SGS/MIN-SLK is a general-purpose algorithm. Our application to the resolution of all of the 140 problems in MPSPLib led us to conclude that the results we obtained were even better than other algorithms that had to be adapted ad-hoc to solve a particular problem.

6 Conclusions

In this work, we have presented the algorithm P-SGS/MIN-SLK. It is based on a heuristic proposed by Kolisch (1996) to solve the Resource-Constrained Project Scheduling Problem (RCPSP). We have adapted the heuristic by Kolisch to the multi-project case (RCMPSP). We have described the functioning of P-SGS/MIN-SLK and, for illustrative purposes, we have also presented how the algorithm deals with the scheduling of a simplified set of projects. In order to evaluate the performance of the algorithm, we used it to solve all of the 140 scheduling problems collected in a well-known repository of RCMPSP problems: the library MPSPLib.

Table 1 summarizes the performance of the algorithm. The complete benchmark can be found in the appendix to this article.

	PSGSMINSLK holds the best result	PSGSMINSLK is least as good as the best heuristic	The difference with the best result is smaller than 1%	The difference with the best result is smaller than 2%	The difference with the best result is smaller than 5%	
Number of problems (out of 140)	22	38	54	71	108	
Percentage	16%	27%	39%	51%	77%	

Table 1. Performance of PSGSMINSLK compared to other algorithms in MPSPLib

We found that the algorithm P-SGS/MIN-SLK outperforms many other heuristics published in this library in spite of its simplicity. Evidence of that is the fact that it provides a better result than any other algorithm in the library in 22 of the 140 problems (i.e. 16% of the cases), and it performs at least as good as other algorithms in 38 of the 140 problems (i.e. 27% of the cases).

In practical terms, when considering the use of P-SGS/MIN-SLK to solve a multi-project problem, it should be noticed that it leads to powerful results even in those cases in which the top result of the benchmark is held by other algorithm. Concretely, we found that the difference between performance of P-SGS/MIN-SLK and the performance of the currently best algorithm in MPSPLib is smaller than 1% in 39% of the problems; smaller than 2% in over half of the problems, and smaller than 5% in 77% of the cases (Table 1). We would like to close by saying that this difference is smaller than 10% in 135 of the 140 RCMPSP cases in MPSPLib even though P-SGS/MIN-SLK is a general-purpose algorithm whilst some other algorithms on MPSPLib were built ad-hoc to solve concrete problems in the library.

In order to increase the usability of the algorithm, in future work we will enhance P-SGS/MIN-SLK's priority rule so that it also considers some practical criteria for companies when prioritizing some activities over others, such as financing constraints.

Compliance with ethical standards

Funding. This research has been partially financed by the project ABARNET (Agent-Based Algorithms for Railway NETworks optimization) financed by the Spanish Ministry of Economy, Industry and Competitiviness, with grant DPI2016-78902-P, and the Computational Models for Industrial Management (CM4IM) project, funded by the Valladolid University General Foundation.

Conflict of interest. The authors declare that there is no conflict of interests regarding the publication of this paper.

Human and animals participants. This article does not contain any studies with human participants or animals performed by any of the authors.

References

- Acebes F, Pereda M, Poza D, et al (2015) Stochastic earned value analysis using Monte Carlo simulation and statistical learning techniques. Int J Proj Manag. doi: 10.1016/j.ijproman.2015.06.012
- Algan M, Roy B, Simonard M (1962) Principes d'une méthode d'exploration de certains domaines et application à l'ordonnancement de la construction de grands ensembles.
- Alvarez-Valdés Olaguíbel R, Tamarit Goerlich JM (1993) The project scheduling polyhedron: Dimension, facets and lifting theorems. Eur J Oper Res 67:204–220. doi: 10.1016/0377-2217(93)90062-R
- Araúzo Araúzo JA, Pajares J, López-Paredes A (2010) Simulating the dynamic scheduling of project portfolios. Simul Model Pract Theory 18:1428–1441. doi: 10.1016/j.simpat.2010.04.008
- Barr RS, Golden BL, Kelly JP, et al (1995) Designing and reporting on computational experiments with heuristic methods. J Heuristics 1:9–32.
- Bartusch M, Möhring RH, Radermacher FJ (1988) Scheduling project networks with resource constraints and time windows. Ann Oper Res 16:199–240.
- Blazewicz J, Lenstra JK, Rinnooy Kan AHG (1983) Scheduling subject to resource constraints: classification and complexity. Discret Appl Math 5:11–24.
- Boctor FF (1990) Some efficient multi-heuristic procedures for resource-constrained project scheduling. Eur J Oper Res 49:3–13. doi: 10.1016/0377-2217(90)90116-S
- Brucker P, Drexl A, Möhring R, et al (1999) Resource-constrained project scheduling: Notation, classification, models, and methods. Eur J Oper Res 112:3–41.
- Confessore G, Giordani S, Rismondo S (2007) A market-based multi-agent system model for decentralized multi-project scheduling. Ann Oper Res 150:115–135. doi: 10.1007/s10479-006-0158-9
- Confessore G, Roma S, Giordani S, Rismondo S (2002) An auction based approach in decentralized project scheduling. In: Proceedings of the 8th international workshop on project management and scheduling. pp 110–113
- Dalfard VM., Ranjbar V. (2012) Multi-projects scheduling with resource constraints & priority rules by the use of simulated annealing algorithm [Programiranje više projekata uz ograničena sredstva & Pravila prioriteta primjenom algoritma simuliranog žarenja]. Teh Vjesn 19:493–499.
- Davis EW (1969) An exact algorithm for the multiple constrained project scheduling problem. Yale University
- Demeulemeester EL, Herroelen WS (2002) Project Scheduling: A Research Handbook.
- Fendley LG (1968) Towards the development of a complete multi-project scheduling system. J Ind Eng 505-515.
- Fink A, Homberger J (2013) An ant-based coordination mechanism for resource-constrained project scheduling with multiple agents and cash flow objectives. Flex Serv Manuf J 25:94–121. doi: 10.1007/s10696-012-9136-5
- Fink A, Homberger J (2015) Decentralized Multi-Project Scheduling. In: Schwindt C, Zimmermann J (eds) Handbook on Project Management and Scheduling Vol. 2. Springer International Publishing, Cham, pp 685–706
- Hartmann S, Briskorn D (2010) A survey of variants and extensions of the resource-constrained project scheduling problem. Eur. J. Oper. Res. 207:1–14.
- Hartmann S, Kolisch R (2000) Experimental evaluation of state-of-the-art heuristics for the resource-constrained project scheduling problem. Eur J Oper Res 127:394–407.
- Herroelen W (2005) Project Scheduling-Theory and Practice. Prod Oper Manag 14:413–432. doi: 10.1111/j.1937-5956.2005.tb00230.x
- Homberger J (2007) A multi-agent system for the decentralized resource-constrained multi-project scheduling problem. Int Trans Oper Res 14:565–589. doi: 10.1111/j.1475-3995.2007.00614.x
- Kaplan LA (1996) Resource-constrained project scheduling with preemption of jobs. UMI
- Kelley JE, Walker MR (1959) Critical-Path Planning and Scheduling. Pap Present December 1-3, 1959, East Jt IRE-AIEE-ACM Comput Conf IRE-AIEE-ACM '59 32:160–173. doi: 10.1145/1460299.1460318

Kelley JEJ (1963) The Critical Path Method: Resources Planning and Scheduling. Ind Sched 347–365.

- Klein R (2000) Scheduling of Resource-Constrained Projects, Volumen 10. Kluwer Academic Publishers
- Kolisch R (1996a) Efficient priority rules for the resource-constrained project scheduling problem. J Oper Manag 14:179–192. doi: 10.1016/0272-6963(95)00032-1
- Kolisch R (1996b) Serial and parallel resource-constrained project scheduling methods revisited: Theory and computation. Eur J Oper Res 90:320–333. doi: 10.1016/0377-2217(95)00357-6
- Kolisch R, Hartmann S (1999) Heuristic Algorithms for the Resource-Constrained Project Scheduling Problem: Classification and Computational Analysis. Proj Sched 14:147–178. doi: 10.1007/978-1-4615-5533-9_7
- Kolisch R, Sprecher A (1996) PSPLIB A project scheduling problem library. Eur J Oper Res 96:205-216.
- Kolisch R, Sprecher a., Drexl a. (1995) Characterization and Generation of a General Class of Resource-Constrained Project Scheduling Problems. Manage Sci 41:1693–1703. doi: 10.1287/mnsc.41.10.1693
- Kurtulus I, Davis EW (1982) Multi-Project Scheduling: Categorization of Heuristic Rules Performance. Manage Sci 28:161–172.
- Lova A, Tormos P (2001) Analysis of Scheduling Schemes and Heuristic Rules Performance in Resource-Constrained Multiproject Scheduling. Ann Oper Res 102:263–286. doi: 10.1023/A:1010966401888
- Lova A, Tormos P, Barber F (2006) Multi-mode resource constrained project scheduling: Scheduling schemes, priority rules and mode selection rules. Intel Artif 10:69–86. doi: 10.4114/ia.v10i30.947
- Malcolm DG, Roseboom JH, Clark CE, Fazar W (1959) Application of a Technique for Research and Development Program Evaluation. Oper Res 7:646–669. doi: 10.1287/opre.7.5.646
- Mingozzi A, Maniezzo V, Ricciardelli S, Bianco L (1998) An Exact Algorithm for the Resource-Constrained Project Scheduling Problem Based on a New Mathematical Formulation. Manage Sci 44:714–729. doi: 10.1287/mnsc.44.5.714
- Özdamar L, Ulusoy G (1995) A survey on the resource-constrained project scheduling problem. IIE Trans 27:574–586. doi: 10.1080/07408179508936773
- Patterson J (1973) Alternate methods of project scheduling with limited resources. Nav Res Logist Q 20:767–784. doi: 10.1002/nav.3800200415
- Patterson JH (1984) A comparison of exact approaches for solving the multiple constrained resource, project scheduling problem. Manage Sci 30:854–867. doi: 10.1287/mnsc.30.7.854
- Pérez E, Posada M, Lorenzana A (2015) Taking advantage of solving the resource constrained multi-project scheduling problems using multi-modal genetic algorithms. Soft Comput. doi: 10.1007/s00500-015-1610-z
- Pritsker AAB, Watters LJ, Wolfe PM (1969) Multiproject Scheduling with Limited Resources: A Zero-One Programming Approach. Manage Sci 16:93–108.
- Schirmer A (1996) New Insights on the Complexity of Resource-Constrained Project Scheduling A Case of Single-Mode Scheduling.
- Semwal VB, Mondal K, Nandi GC (2017) Robust and accurate feature selection for humanoid push recovery and classification: deep learning approach. Neural Comput Appl 28:565–574. doi: 10.1007/s00521-015-2089-3
- Semwal VB, Raj M, Nandi GC (2015) Biometric gait identification based on a multilayer perceptron. Rob Auton Syst 65:65–75. doi: 10.1016/j.robot.2014.11.010
- Semwal VB, Singha J, Sharma PK, et al (2016) An optimized feature selection technique based on incremental feature analysis for bio-metric gait data classification. Multimed Tools Appl 1–19. doi: 10.1007/s11042-016-4110-y
- Song W, Kang D, Zhang J, Xi H (2016) Decentralized Multi-Project Scheduling via Multi-Unit Combinatorial Auction. Aamas 2016 836–844.
- Vázquez EP, Calvo MP, Ordóñez PM (2013) Learning process on priority rules to solve the RCMPSP. J Intell Manuf 26:123–138. doi: 10.1007/s10845-013-0767-5
- Villafañez F, Lopez-Paredes A, Pajares J, de la Fuente D (2014a) From the RCPSP to the DRCMPSP: Methodological foundations. In: Proceedings on the International Conference on Artificial Intelligence (ICAI); Athens: 1-6. Athens: The Steering Committee of The World Congress in Computer Science,

Computer Engineering and Applied Computing (WorldComp).

- Villafañez F, Lopez-Paredes A, Pajares J, de la Fuente D (2014b) From the RCPSP to the DRCMPSP: Methodological foundations. In: Proceedings on the International Conference on Artificial Intelligence (ICAI). p 1
- Villafáñez F, Poza DJ (2010) Propuesta de Modelo MAS para la resolución del RCMPSP basado en Subastas Combinatorias. In: Gutiérrez Pajares J, López-Paredes A, Iglesias Hernández C (eds) Best Practices in Project Management. Methodologies and case studies in Construction and Engineering.
- Wauters M, Vanhoucke M (2017) A Nearest Neighbour extension to project duration forecasting with Artificial Intelligence. Eur J Oper Res 259:1097–1111. doi: 10.1016/j.ejor.2016.11.018
- Wauters T, Verbeeck K, De Causmaecker P, Berghe G Vanden (2015) A learning-based optimization approach to multi-project scheduling. J Sched 18:61–74.
- Zheng Z, Guo Z, Zhu Y, Zhang X (2014) A critical chains based distributed multi-project scheduling approach. Neurocomputing 143:282–293.

Appendix

The following table compares the performance of P-SGS/MIN-SLK and the performance of the current leading algorithm for each one of the 140 problems in MPSPLib. For this aim, the table shows two entries per problem expect in those cases where P-SGS/MIN-SLK holds the best result, where only one entry is shown, Notice that the 38 (out of 140) RCMPSP problems in which PSGSMINSLK holds the best result in TMS are shown in shaded cells.

The name of the problems in MPSPLib are conveniently codified so that their names reflect the number and the size of the projects. For example, the first problem is named mp_j30_a10_nr1 meaning the following: a multi-project problem (mp) composed of 10 projects (a10) each of which has 30 activities (j30). The term nr1 is simply a reference to distinguish different problems with the same number of project and activities. For example, all of the first five problems have 10 projects and 30 activities (nr_1 to nr_5) which differ in the start dates of the projects and the number of global resources (2, 1, 2, 3, and 1, respectively). In the last 80 problems of the list, the suffix _AC is added to the name of the problem, which means that all the resources of that problem are global.

ID	MPSPlib INSTANCE	NO. OF TASKS	NO. OF PROJECTS	NO. OF GLOB. RESOURCES	AUTHOR	TMS	DATE	METHOD
1	mp_j30_a10_nr1	30	10	2	Tony Wauters Lopez-Paredes/Pajares/Villafañez	188 188	8/3/10 6/18/14	HYPER PSGSMINSLK
2	mp_j30_a10_nr2	30	10	1	Túlio Toffolo Lopez-Paredes/Pajares/Villafañez	109 114	7/2/14 6/18/14	MATHEUR PSGSMINSLK
3	mp_j30_a10_nr3	30	10	2	Lopez-Paredes/Pajares/Villafañez	243	6/18/14	PSGSMINSLK
4	mp_j30_a10_nr4	30	10	3	Lopez-Paredes/Pajares/Villafañez	143	6/18/14	PSGSMINSLK
5	mp_j30_a10_nr5	30	10	1	Lopez-Paredes/Pajares/Villafañez	187	6/18/14	PSGSMINSLK
6	mp_j30_a2_nr1	30	2	2	pérez/posada Lopez-Paredes/Pajares/Villafañez	70 71	10/28/13 6/18/14	GA-RK PSGSMINSLK
7	mp_j30_a2_nr2	30	2	1	pérez/posada Lopez-Paredes/Pajares/Villafañez	58 61	10/28/13 6/18/14	GA-RK PSGSMINSLK

8	mp_j30_a2_nr3	30	2	2	Trautmann/Homberger	65 65	5/14/08 6/18/14	MAS/PS
9	mp i30 a2 nr4	30	2	3	Dietz/Homberger	54	5/20/08	CMAS/ES-STV
10	mp j30 a2 nr5	30	2	1	Lopez-Paredes/Pajares/Villafañez Ameisenbär(Daniela)	58 58	6/18/14 2/14/11	PSGSMINSLK CMAS/ES
44		20	20	2	Birkner/Homberger	59 417	7/5/08	CMAS/ES-
	mp_j30_az0_nn	30	20	2	Lopez-Paredes/Pajares/Villafañez	425	6/18/14	PSGSMINSLK
12	mp_j30_a20_nr2	30	20	1	Lopez-Paredes/Pajares/Villafañez	278	6/18/14	PSGSMINSLK
13	mp_j30_a20_nr3 mp_j30_a20_nr4	30	20	3	Lopez-Paredes/Pajares/Villatanez	183	6/18/14	PSGSMINSLK
15	mp_j30_a20_nr5	30	20	1	Tony Wauters Lopez-Paredes/Pajares/Villafañez	410	1/21/14 6/18/14	MINTWK
16	mp_j30_a5_nr1	30	5	2	pérez/posada Lopez-Paredes/Pajares/Villafañez	82 83	10/27/14 6/18/14	GA-RK PSGSMINSLK
17	mp_j30_a5_nr2	30	5	1	Tony Wauters Lopez-Paredes/Pajares/Villafañez	79 80	6/14/12 6/18/14	GT-MAS PSGSMINSLK
18	mp_j30_a5_nr3	30	5	2	Tony Wauters Lopez-Paredes/Pajares/Villafañez	103 108	6/27/12 6/18/14	HYPER PSGSMINSLK
19	mp_j30_a5_nr4	30	5	3	Dietz/Homberger Lopez-Paredes/Pajares/Villafañez	76 76	5/10/08 6/18/14	RES PSGSMINSLK
20	mp_j30_a5_nr5	30	5	1	Dietz/Homberger Lopez-Paredes/Pajares/Villafañez	87 88	6/26/08 6/18/14	CMAS/ES-STV PSGSMINSLK
21	mp_j90_a10_nr1	90	10	2	Dietz/Homberger Lopez-Paredes/Pajares/Villafañez	158	5/14/08 6/19/14	CMAS/ES PSGSMINSLK
22	mp_j90_a10_nr2	90	10	1	Lopez-Paredes/Pajares/Villafañez	128	6/19/14	PSGSMINSLK
23	mp_j90_a10_nr3	90	10	2	Lopez-Paredes/Pajares/Villafañez	213	6/19/14	PSGSMINSLK
24	mp_j90_a10_nr4	90	10	3	Dietz/Homberger Lopez-Paredes/Paiares/Villafañez	150 150	5/10/08 6/19/14	RES PSGSMINSLK
25	mp i90 a10 pr5	90	10	1	Tony Wauters	230	6/11/12	GT-MAS
25	mp_joo_aro_mo	50	10	I	Lopez-Paredes/Pajares/Villafañez	236	6/19/14	PSGSMINSLK
26	mp_j90_a2_nr1	90	2	2	Lopez-Paredes/Pajares/Villafañez	88	6/19/14	PSGSMINSLK
27	mp_j90_a2_nr2	90	2	1	Túlio Toffolo Lopez-Paredes/Pajares/Villafañez	117 124	7/2/14 6/19/14	MATHEUR PSGSMINSLK
28	mp_j90_a2_nr3	90	2	2	Dietz/Homberger Lopez-Paredes/Pajares/Villafañez	114 115	5/10/08 6/19/14	RES PSGSMINSLK
29	mp_j90_a2_nr4	90	2	3	Dietz/Homberger Lopez-Paredes/Pajares/Villafañez	92 92	5/10/08 6/19/14	RES PSGSMINSLK
30	mp_j90_a2_nr5	90	2	1	Dietz/Homberger Lopez-Paredes/Pajares/Villafañez	121	6/25/08 6/19/14	CMAS/ES PSGSMINSLK
31	mp_j90_a20_nr1	90	20	2	I ony Wauters Lopez-Paredes/Pajares/Villafañez	97 110	10/22/09 6/19/14	GT-MAS PSGSMINSLK
32	mp_j90_a20_nr2	90	20	1	Lopez-Paredes/Pajares/Villafañez	164	6/19/14 6/19/14	PSGSMINSLK
33	mp_j90_a20_nr3	90	20	2	Lopez-Paredes/Pajares/Villafañez	122	5/10/08 6/19/14	PSGSMINSLK
34	mp_j90_a20_nr4	90	20	3	Lopez-Paredes/Pajares/Villafañez	186	6/19/14	PSGSMINSLK
35	mp_j90_a20_nr5	90	20	1	Lopez-Paredes/Pajares/Villafañez	229	6/19/14	PSGSMINSLK
36	mp_j90_a5_nr1	90	5	2	Lopez-Paredes/Pajares/Villafañez	79 79 114	5/14/08 6/19/14	PSGSMINSLK
37	mp_j90_a5_nr2	90	5	1	Lopez-Paredes/Pajares/Villafañez	114	6/19/14	PSGSMINSLK
38	mp_j90_a5_nr3	90	5	2	Dietz/Homberger Lopez-Paredes/Pajares/Villafañez	138 140	5/10/08 6/19/14	PSGSMINSLK
39	mp_j90_a5_nr4	90	5	3	Dietz/Homberger Lopez-Paredes/Pajares/Villafañez	123 132	5/10/08 6/19/14	
40	mp_j90_a5_nr5	90	5	1	Lopez-Paredes/Pajares/Villafañez	162	6/19/14	PSGSMINSLK
41	mp_j120_a10_nr1	120	10	2	Dietz/Homberger Lopez-Paredes/Pajares/Villafañez	130 134	5/14/08 6/20/14	PSGSMINSLK
42	mp_j120_a10_nr2	120	10	1	Tony Wauters Lopez-Paredes/Pajares/Villafañez	248 265	6/14/12 6/20/14	GT-MAS PSGSMINSLK
43	mp_j120_a10_nr3	120	10	2	Dietz/Homberger Lopez-Paredes/Pajares/Villafañez	142 146	5/10/08 6/20/14	RES PSGSMINSLK
44	mp_j120_a10_nr4	120	10	3	Dietz/Homberger	371	5/10/08	RES BSGSMINSLK
45	mp_j120_a10_nr5	120	10	1	Lopez-Paredes/Pajares/Villafañez	481	6/20/14	PSGSMINSLK
46	mp_j120_a2_nr1	120	2	2	Tony Wauters Lopez-Paredes/Pajares/Villafañez	155 161	6/28/12 6/20/14	HYPER PSGSMINSLK
47	mp_j120_a2_nr2	120	2	1		133	7/2/14	MATHEUR
48	mp j120 a2 nr3	120	2	2	Lopez-Paredes/Pajares/Villafañez	275	6/20/14	PSGSMINSLK
49	mp_j120_a2_nr4	120	2	3		148	7/2/14	MATHEUR
50	mp_j120_a2_nr5	120	2	1	Túlio Toffolo	108	6/20/14 7/2/14	MATHEUR
51	mp_j120_a20_nr1	120	20	2	Túlio Toffolo	76	7/2/14	
52	mp_j120_a20_nr2	120	20	1	Túlio Toffolo	204	7/2/14	
53	mp_j120_a20_nr3	120	20	2	Túlio Toffolo	235	7/2/14	
54	mp_j120_a20_nr4	120	20	3	Túlio Toffolo Lopez-Paredes/Paiares/Villafañez	203	7/2/14 6/20/14	MATHEUR PSGSMINSI K
55	mp_j120_a20_nr5	120	20	1	Túlio Toffolo Lopez-Paredes/Paiares/Villafañez	178	7/2/14 6/20/14	MATHEUR PSGSMINSI K
56	mp i120 a5 nr1	120	5	2	Túlio Toffolo	75	7/2/14	MATHEUR
57	mp_j120_a5_nr2	120	5	- 1	Lopez-Paredes/Pajares/Villafañez Túlio Toffolo	83 165	6/20/14 7/2/14	PSGSMINSLK MATHEUR

					Lopez-Paredes/Pajares/Villafañez	181	6/20/14	PSGSMINSLK
58	mp_j120_a5_nr3	120	5	2	Dietz/Homberger	200	5/10/08	RES
		100	-	0	Dietz/Homberger	188	5/10/08	RES
59	mp_j120_a5_nr4	120	5	3	Lopez-Paredes/Pajares/Villafañez	188	6/20/14	PSGSMINSLK
60	mp_j120_a5_nr5	120	5	1	Lopez-Paredes/Pajares/Villatanez	688	5/16/08	CMAS/ES
61	mp_j90_a10_nr5_AC1	90	10	4	Lopez-Paredes/Pajares/Villafañez	689	6/23/14	PSGSMINSLK
62	mp_j90_a10_nr5_AC10	90	10	4	Dietz/Homberger Lopez-Paredes/Paiares/Villafañez	172 176	5/15/08 6/23/14	CMAS/ES PSGSMINSLK
63	mp i90 a10 pr5 AC2	90	10	4	Dietz/Homberger	732	5/16/08	CMAS/ES
00	mp_j30_a10_m3_A02	50	10	7	Lopez-Paredes/Pajares/Villafañez	736	6/23/14	PSGSMINSLK
64	mp_j90_a10_nr5_AC3	90	10	4	Lopez-Paredes/Pajares/Villafañez	203 264	6/23/14	PSGSMINSLK
65	mp_j90_a10_nr5_AC4	90	10	4	Túlio Toffolo	667 683	7/2/14	MATHEUR
66		00	10	4	Dietz/Homberger	361	6/27/08	CMAS/ES-STV
00	11p_j90_a10_115_AC5	90	10	4	Lopez-Paredes/Pajares/Villafañez	368	6/23/14	PSGSMINSLK
67	mp_j90_a10_nr5_AC6	90	10	4	Lopez-Paredes/Pajares/Villafañez	685	6/23/14	PSGSMINSLK
68	mp_j90_a10_nr5_AC7	90	10	4	Lopez-Paredes/Pajares/Villafañez	390	6/23/14	PSGSMINSLK
69	mp_j90_a10_nr5_AC8	90	10	4	Dietz/Homberger Lopez-Paredes/Paiares/Villafañez	273 275	5/16/08 6/23/14	RES PSGSMINSLK
70	mp i90 a10 nr5 AC9	90	10	4	Túlio Toffolo	233	7/2/14	MATHEUR
			10		Lopez-Paredes/Pajares/Villafañez	243	6/23/14 5/16/08	PSGSMINSLK
71	mp_j90_a20_nr5_AC1	90	20	4	Lopez-Paredes/Pajares/Villafañez	447	6/23/14	PSGSMINSLK
72	mp_j90_a20_nr5_AC10	90	20	4	Dietz/Homberger	483	5/15/08 6/23/14	CMAS/ES
72	mp i00 o20 pr5 AC2	00	20	4	Dietz/Homberger	127	5/15/08	CMAS/ES
75	111p_190_az0_1113_A02	30	20	4	Lopez-Paredes/Pajares/Villafañez	130	6/23/14	PSGSMINSLK
74	mp_j90_a20_nr5_AC3	90	20	4	Lopez-Paredes/Pajares/Villafañez	167	6/23/14	PSGSMINSLK
75	mp_j90_a20_nr5_AC4	90	20	4	Lopez-Paredes/Pajares/Villafañez	365	6/23/14	PSGSMINSLK
76	mp_j90_a20_nr5_AC5	90	20	4	Dietz/Homberger Lopez-Paredes/Paiares/Villafañez	123 130	5/15/08 6/23/14	CMAS/ES PSGSMINSLK
77	mp i90 a20 nr5 AC6	90	20	4	Dietz/Homberger	236	5/16/08	CMAS/ES
			20		Lopez-Paredes/Pajares/Villafañez	244	6/23/14	PSGSMINSLK
78	mp_j90_a20_nr5_AC7	90	20	4	Birkner/Homberger	270	7/6/08	BORDA
70	mp i00 220 pr5 AC8	00	20	4	Lopez-Paredes/Pajares/Villafañez	274	6/23/14	PSGSMINSLK PSGSMINSLK
- 19	mp_j90_a20_ni5_AC0	90	20	4	Tony Wauters	426	6/15/12	GT-MAS
80	111p_J90_az0_1115_AC9	90	20	4	Lopez-Paredes/Pajares/Villafañez	439	6/23/14	PSGSMINSLK
81	mp_j90_a2_nr5_AC1	90	2	4	Lopez-Paredes/Pajares/Villafañez	192	6/23/14	PSGSMINSLK
82	mp j90 a2 nr5 AC10	90	2	4	Dietz/Homberger	105	5/15/08	CMAS/ES
			2		Dietz/Homberger	333	5/20/08	CMAS/ES
83	mp_j90_a2_nr5_AC2	90	2	4	Lopez-Paredes/Pajares/Villafañez	347	6/23/14	PSGSMINSLK
84	mp_j90_a2_nr5_AC3	90	2	4	Túlio Toffolo Lopez-Paredes/Paiares/Villafañez	160 174	7/2/14 6/23/14	MATHEUR PSGSMINSLK
85	mp i90 a2 nr5 AC4	90	2	4	Túlio Toffolo	329	7/2/14	MATHEUR
					Lopez-Paredes/Pajares/Villatanez Dietz/Homberger	352 72	6/23/14 5/15/08	CMAS/ES
86	mp_j90_a2_nr5_AC5	90	2	4	Lopez-Paredes/Pajares/Villafañez	72	6/23/14	PSGSMINSLK
87	mp_j90_a2_nr5_AC6	90	2	4	Dietz/Homberger Lopez-Paredes/Paiares/Villafañez	186 190	5/15/08 6/23/14	CMAS/ES PSGSMINSLK
88	mp i90 a2 pr5 AC7	90	2	4	Túlio Toffolo	330	7/2/14	MATHEUR
	mp_joo_az_mo_xov	00	<u> </u>	7	Lopez-Paredes/Pajares/Villafañez	345	6/23/14	PSGSMINSLK MATHEUR
89	mp_j90_a2_nr5_AC8	90	2	4	Lopez-Paredes/Pajares/Villafañez	168	6/23/14	PSGSMINSLK
90	mp_j90_a2_nr5_AC9	90	2	4	Túlio Toffolo	329 352	7/2/14	MATHEUR PSGSMINSI K
01		00	F	4	Dietz/Homberger	568	5/16/08	RES
91	IIIp_J90_a5_III5_AC1	90	5	4	Lopez-Paredes/Pajares/Villafañez	572	6/23/14	
92	mp_j90_a5_nr5_AC10	90	5	4	Lopez-Paredes/Pajares/Villafañez	∠54 258	6/23/14	PSGSMINSLK
93	mp_j90_a5_nr5_AC2	90	5	4	Túlio Toffolo	628	7/2/14	MATHEUR
			-		Dietz/Homberger	317	5/16/08	CMAS/ES
94	mp_j90_a5_nr5_AC3	90	5	4	Lopez-Paredes/Pajares/Villafañez	341	6/23/14	PSGSMINSLK
95	mp_j90_a5_nr5_AC4	90	5	4	Lopez-Paredes/Pajares/Villafañez	816 858	7/2/14 6/23/14	PSGSMINSLK
96	mp i90 a5 nr5 AC5	90	5	4	Dietz/Homberger	256	6/12/08	RES
			-		Lopez-Paredes/Pajares/Villatanez	263 568	6/23/14 5/15/08	CMAS/ES
97	mp_J90_a5_nr5_AC6	90	5	4	Lopez-Paredes/Pajares/Villafañez	572	6/23/14	PSGSMINSLK
98	mp_j90_a5_nr5_AC7	90	5	4	Dietz/Homberger	630 632	5/15/08 6/23/14	CMAS/ES PSGSMINSI K
90	mp i90 a5 pr5 AC8	٩n	5	4	Dietz/Homberger	317	5/16/08	RES
	p_joo_do_iiio_A00	50	5	т	Lopez-Paredes/Pajares/Villafañez	326	6/23/14	MATHEUD
100	mp_j90_a5_nr5_AC9	90	5	4	Lopez-Paredes/Pajares/Villafañez	860	6/23/14	PSGSMINSLK
101	mp_j120_a10_nr5_AC1	120	10	4	Lopez-Paredes/Pajares/Villafañez	763	6/24/14	PSGSMINSLK
102	mp_j120_a10_nr5_AC10	120	10	4	Dietz/Homberger Lopez-Paredes/Pajares/Villafañez	186	5/15/08 6/24/14	PSGSMINSLK
103	mp j120 a10 nr5 AC2	120	10	4	Dietz/Homberger	378	5/16/08	CMAS/ES
104	mp i120 a10 nr5 AC3	120	10	4	Lopez-Paredes/Pajares/Villatañez	379	6/24/14	PSGSMINSLK PSGSMINSLK
105	mp i120 a10 nr5 AC4	120	10	4	Dietz/Homberger	416	5/16/08	CMAS/ES
106	mp i120 a10 nr5 AC5	120	10	4	Lopez-Paredes/Pajares/Villafañez	419 390	6/24/14 5/17/08	PSGSMINSLK RES
	,_,_,,,,,,,	0		•	2.012.1.01.1201901	500	2, 30	

				Lopez-Paredes/Pajares/Villafañez	399	6/24/14	PSGSMINSLK
107 mp_j120_a10_nr5_AC6	120	10	4	Dietz/Homberger	384	5/16/08	CMAS/ES
100 mm i120 a10 mF AC7	100	10	4	Dietz/Homberger	138	5/17/08	RES
108 hp_j120_a10_hi5_AC7	120	10	4	Lopez-Paredes/Pajares/Villafañez	143	6/24/14	PSGSMINSLK
109 mp_j120_a10_nr5_AC8	120	10	4	Dietz/Homberger	169	5/17/08	RES
				Dietz/Homberger	174	5/16/08	CMAS/ES
110 mp_j120_a10_nr5_AC9	120	10	4	Lopez-Paredes/Pajares/Villafañez	160	6/24/14	PSGSMINSLK
111 mp i120 a20 nr5 AC1	120	20	4	Dietz/Homberger	380	6/13/08	CMAS/SA
				Lopez-Paredes/Pajares/Villatanez	380	6/24/14	CMAS/ES
112 mp j120 a20 nr5 AC10	120	20	4	Birkner/Homberger	342	7/5/08	BORDA
				Lopez-Paredes/Pajares/Villafañez	345	6/24/14	PSGSMINSLK
113 mp_j120_a20_nr5_AC2	120	20	4	Dietz/Homberger	301	6/14/08	RES
114 mp i120 a20 pr5 AC3	120	20	4	Lopez-Paredes/Pajares/Villafañez	968	6/24/14	PSGSMINSLK
115 mp i120 a20 pr5 AC4	120	20		Dietz/Homberger	308	5/17/08	RES
115 hp_j120_a20_hi5_AC4	120	20	4	Lopez-Paredes/Pajares/Villafañez	314	6/24/14	PSGSMINSLK
116 mp_j120_a20_nr5_AC5	120	20	4	Dietz/Homberger	350	5/17/08	RES
117 mp i120 a20 pr5 AC6	120	20	4	Lopez-Paredes/Pajares/Villafañez	863	6/24/14	PSGSMINSLK
118 mp j120 a20 nr5 AC7	120	20	4	Lopez-Paredes/Pajares/Villafañez	813	6/24/14	PSGSMINSLK
119 mp_j120_a20_nr5_AC8	120	20	4	Lopez-Paredes/Pajares/Villafañez	364	6/24/14	PSGSMINSLK
120 mp i120 a20 nr5 AC9	120	20	4	Dietz/Homberger	297	5/17/08	RES
	-	-		Lopez-Paredes/Pajares/Villatanez	300	6/24/14	PSGSMINSLK
121 mp_j120_a2_nr5_AC1	120	2	4	Lopez-Paredes/Pajares/Villafañez	213	6/23/14	PSGSMINSLK
122 mp i120 22 pr5 AC10	120	2	4	Dietz/Homberger	92	5/15/08	CMAS/ES
122 11p_120_az_115_AC10	120	Z	4	Lopez-Paredes/Pajares/Villafañez	100	6/23/14	PSGSMINSLK
123 mp_j120_a2_nr5_AC2	120	2	4	Dietz/Homberger	103	5/15/08	CMAS/ES
				Túlio Toffolo	178	7/2/14	MATHEUR
124 mp_j120_a2_nr5_AC3	120	2	4	Lopez-Paredes/Pajares/Villafañez	183	6/23/14	PSGSMINSLK
125 mp j120 a2 nr5 AC4	120	2	4		105	7/2/14	MATHEUR
				Lopez-Paredes/Pajares/Villatanez	95	5/16/08	RES
126 mp_j120_a2_nr5_AC5	120	2	4	Lopez-Paredes/Pajares/Villafañez	106	6/23/14	PSGSMINSLK
				Túlio Toffolo	212	7/2/14	MATHEUR
<u>127 mp_j120_a2_nr5_AC6</u>	120	2	4	Lopez-Paredes/Pajares/Villafañez	224	6/23/14	PSGSMINSLK
128 mp_j120_a2_nr5_AC7	120	2	4	Dietz/Homberger	101 107	5/16/08 6/23/14	RES PSGSMINSI K
100	100	0		Dietz/Homberger	178	5/16/08	RES
129 mp_120_a2_nr5_AC8	120	2	4	Lopez-Paredes/Pajares/Villafañez	185	6/23/14	PSGSMINSLK
130 mp_j120_a2_nr5_AC9	120	2	4	Túlio Toffolo	96 107	7/2/14	MATHEUR
				Dietz/Homberger	581	6/13/08	CMAS/ES
131 mp_j120_a5_nr5_AC1	120	5	4	Lopez-Paredes/Pajares/Villafañez	600	6/23/14	PSGSMINSLK
132 mp i120 a5 pr5 AC10	120	5	4	Dietz/Homberger	614	5/16/08	RES
102 mp_120_40_100_1010	.20	0	•	Lopez-Paredes/Pajares/Villafañez	628	6/24/14	PSGSMINSLK
133 mp_j120_a5_nr5_AC2	120	5	4	Dietz/Homberger	292	6/13/08	
134 mp_j120_a5_nr5_AC3	120	5	4	Lopez-Paredes/Pajares/Villafañez	532	6/23/14	PSGSMINSLK
135 mp i120 a5 nr5 AC4	120	5	4	Dietz/Homberger	372	5/16/08	CMAS/ES
100 mp_120_00_m0_, 10 1	.20	0	•	Lopez-Paredes/Pajares/Villafañez	384	6/23/14	PSGSMINSLK
136 mp_j120_a5_nr5_AC5	120	5	4	Dietz/Homberger Lopez-Paredes/Pajares/Villafañez	632	5/16/08 6/24/14	
137 mp i120 of pr5 ACC	120	E	А	Dietz/Homberger	576	6/28/08	CMAS/ES-STV
	120	5	4	Lopez-Paredes/Pajares/Villafañez	592	6/24/14	PSGSMINSLK
138 mp_j120_a5_nr5_AC7	120	5	4	Dietz/Homberger	284	5/15/08	CMAS/ES
139 mp i120 a5 nr5 AC8	120	5	4	Lopez-Paredes/Paiares/Villafañez	527	6/24/14	PSGSMINSLK
140 mp i120 of or5 AC0	120	E		Dietz/Homberger	355	5/16/08	CMAS/ES
	120	Э	4	Lopez-Paredes/Pajares/Villafañez	369	6/24/14	PSGSMINSLK